

# Analyzing a special case of the Hele-Shaw flow using integro-differential operators

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# The Law of the Instrument

“I suppose it is tempting, if the only tool you have is a hammer, to treat everything as if it were a nail.”

– thanks, wikipedia

## A theme to keep in mind

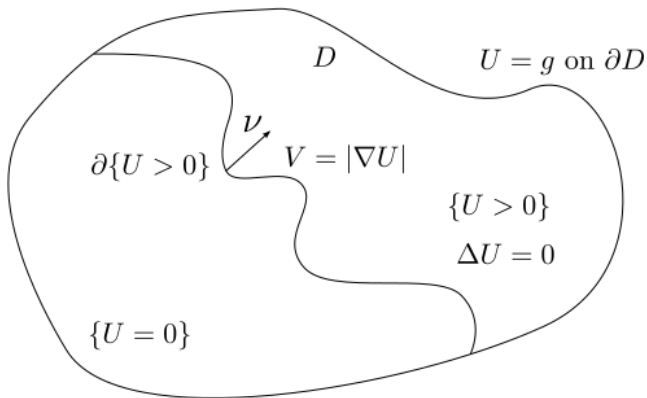
There are a few instances where regularity is shown to occur for Hele-Shaw.

Is it **regularizing**?

Where does it **come from**?

# Hele-Shaw

Let us recall what the one phase Hele-Shaw problem looks like



# Hele-Shaw

A few references for existence, uniqueness, regularity:

- Escher-Simonett 1997
- Kim 2003, 2006
- Jerison-Kim 2005
- Choi-Jerison-Kim 2007
- Chang Lara - Guillen 2016

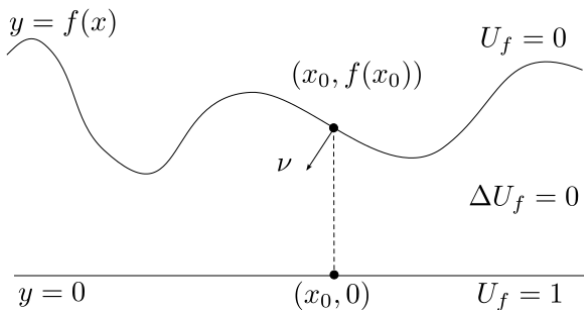
## Hele-Shaw, special case for the interface

Then,  $U : \mathbb{R}_+^{d+1} \times \mathbb{R}_+ \rightarrow \mathbb{R}$  is a non-negative function solving

$$(HS) \begin{cases} \Delta U = 0 & \text{in } \{U > 0\}, \\ U = 1 & \text{on } \{y = 0\}, \\ V = |\nabla U| & \text{on } \partial\{U > 0\}. \end{cases}$$

$V$  denoting the normal velocity of the free boundary  $\partial\{U > 0\}$ .

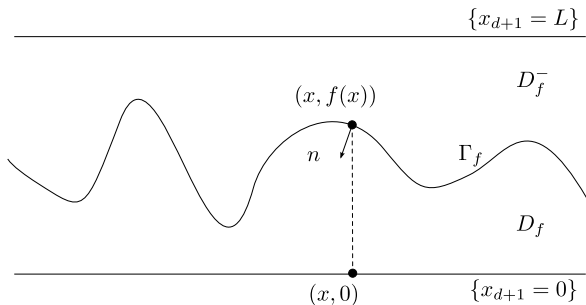
## Hele-Shaw, special case for the interface



$$D_f = \{(x, x_{d+1}) \in \mathbb{R}^{d+1} : 0 < x_{d+1} < f(x)\} \text{ and } \Gamma_f = \text{graph}(f)$$

## Hele-Shaw, special case for the interface

These methods actually apply to a two-phase version of Hele-Shaw



$$V = G(\partial_n^+ U_f^+, \partial_n^- U_f^-) \quad (\text{e.g. } G = |\partial_n^+ U_f^+|^2 - |\partial_n^- U_f^-|^2)$$



## Hele-Shaw, the goal

So, the goal of studying the problem is to produce a function  $U$  and describe its properties.

Thus, in our special case, this is equivalent to producing and describing the function,  $f$ .

# Integro-Differential Equations

$$\partial_t f - L(f, x) = g(x, t) \text{ in } \mathbb{R}^d \times (0, T] \text{ and } f(\cdot, 0) = f_0.$$

Where  $L(f, x)$  has the form

$$L(f, x) = b(x) \cdot \nabla f(x) + \int_{\mathbb{R}^d} (f(x+h) - f(x) - \mathbb{1}_{B_1}(h) \nabla f(x) \cdot h) \mu(x, dh),$$

with

$b$  bounded, and  $\mu(x, \cdot) \geq 0$  is a measure, possibly singular at  $h = 0$ .

$$\text{NOTATION: } \delta_h f(x) := f(x+h) - f(x) - \mathbb{1}_{B_1}(h) \nabla f(x) \cdot h$$

# Integro-Differential Equations

The (arguably) simplest and most canonical case is for some  $\alpha \in (0, 2)$

$$b = 0 \quad \text{and} \quad \mu(x, dh) = C_{d,\alpha} |h|^{-d-\alpha} dh,$$

giving

$$L(f, x) = -(-\Delta)^{\alpha/2} f(x)$$

# Integro-Differential Equations, a powerful tool

## Theorem (Krylov-Safonov)

Under (ASSUMPTIONS, listed below), there exists a universal  $\gamma$ , and  $C$ , so that any (appropriately defined) solution to

$$\partial_t f - L(f, x) = g(x) \text{ in } B_1 \times (-1, 0],$$

enjoys the estimate

$$[f]_{C^\gamma(B_{1/2} \times (-1/2, 0])} \leq C \left( \|f\|_{L^\infty(\mathbb{R}^d \times (-1, 0])} + \|g\|_{L^\infty} \right),$$

where

$$[f]_{C^\gamma(B_{1/2} \times (-1/2, 0])} = \sup_{0 < |x-y| < 1/2, 0 < |t-s| < 1/2} \frac{|f(x, s) - f(y, t)|}{(|x-y| + |s-t|^{1/\alpha})^\gamma}$$

## Some Results for Kyrlov-Safonov

all results assume a density:  $\mu(x, dh) = k(x, h)dh$

symmetry:  $K(x, -h) = K(x, h)$ ,

LB:  $c_1(2 - \alpha) |h|^{-d-\alpha} \leq K(x, h) \leq c_2(2 - \alpha) |h|^{-d-\alpha}$  :UB

## Some Results for Kyrlov-Safonov

- Bass-Levin (2002): elliptic;  $b \equiv 0$ ; symmetry, LB, UB (not robust)
- Bass-Kassmann (2004): elliptic;  $b \equiv 0$ ; variable  $\alpha$ ; symmetry, LB, UB (not robust)
- Silvestre (2006): elliptic;  $b \equiv 0$ ; variable  $\alpha$ ; slightly relaxed symmetry, LB, UB (not robust)
- Caffarelli-Silvestre (2009): elliptic;  $b \equiv 0$ ; symmetry, LB, UB (robust)
- Chang Lara (2012): elliptic; nontrivial  $b$ ; non-symmetric, LB, UB (robust)
- Chang Lara - Davila (2016): parabolic; non-trivial  $b$ ; non-symmetric; LB, UB (robust)
- Silvestre (2014): parabolic; non-trivial  $b$ ; non-symmetric; LB, UB (robust)
- Schwab-Silvestre (2016): parabolic; non-trivial  $b$ ; non-symmetric, relaxed LB, UB only in integral sense (robust)

## For Later Use – Result for Krylov-Safonov

$$\partial_t f - \left( b(x) \cdot \nabla + \int_{\mathbb{R}^d} \delta_y f(x) K(x, y) dy \right) = g(x, t)$$

Theorem (Chang Lara - Davila 2016, also Chang Lara 2012 elliptic)

Assume  $\alpha \in [1, 2)$ . Krylov-Safonov and  $C^{1,\gamma}$  for the class of equations where the pair  $(b, K)$  satisfies

$$\sup_{r \in (0,1)} r^{\alpha-1} \left| b + \int_{B_1 \setminus B_r} y K(x, y) dy \right| \leq C$$

and

$$c_1 |y|^{-d-\alpha} \leq K(x, y) \leq c_2 |y|^{-d-\alpha}.$$

## Krylov-Safonov, fully nonlinear

Note, Krylov-Safonov holds for fully nonlinear equations, for  $f$  a viscosity solution of

$$\partial_t f - F(f, x) = g(x, t) \quad \text{in } B_1 \times (-1, 0],$$

where  $F$  is an operator that enjoys the structure, for some family of  $L^{ij}$  as above,

$$F(f, x) = \min_i \max_j L^{ij}(f, x).$$

(There is much more to say, but not enough time)



## $C^{1,\gamma}$ , translation invariant

If furthermore,  $F$  is translation invariant, i.e.

$F(f(\cdot + z), x) = F(f, x + z)$  (or, concretely,  $b^{ij}$  and  $\mu^{ij}$  are independent of  $x$ ), Krylov-Safonov implies higher regularity

### Theorem ( $C^{1,\gamma}$ , Assume $F$ is translation invariant)

*There is a universal  $\gamma$  and  $C$  (depending upon the assumptions on  $F$ , above) so that if  $f$  is a viscosity solution of  $\partial_t f - F(f, x) = 0$  in  $B_1 \times (-1, 0]$ , then*

$$(*)[\partial_t f(x, \cdot)]_{C^\gamma((-1/2, 0])} + [\nabla f(\cdot, t)]_{C^\gamma(B_{1/2})} \leq C(\|u\|_{L^\infty(\mathbb{R}^d) \times (-1, 0]} + (**))$$

Sometimes  $(*)$  is present and sometimes it is not, sometimes  $(**)$  contains an extra term for the time behavior of  $u$ , and sometimes it doesn't, depending upon the particular result.

See: Chang Lara - Davila 2016 and Serra 2015 (also Kriventsov 2013)

# Operators with the GCP

## Definition

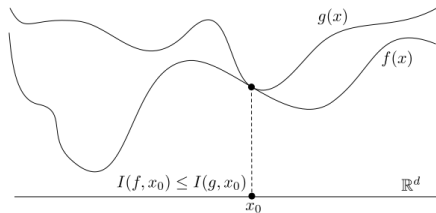
$$I : D \subset \mathbb{R}^X \rightarrow \mathbb{R}^X$$

is said to have the **global comparison property (GCP)** if

$$f, g \in D \text{ and } g \text{ touches } f \text{ from above at } x_0 \Rightarrow I(f, x_0) \leq I(g, x_0)$$

$$f(x) \leq g(x) \quad \forall x \in X$$

$$f(x_0) = g(x_0)$$



## Structure from GCP

### Theorem (Guillen-Schwab 2016 and 2019)

(Generalizes to a complete,  $d$ -dimensional manifold)  
If  $I : C^2(\mathbb{R}^d) \rightarrow C^0(\mathbb{R}^d)$  is Lipschitz, with the GCP, then

$$\forall u \in C^2, x \in \mathbb{R}^d, I(u, x) = \min_i \max_j \{f_{ij}(x) + L_{ij}(u, x)\}$$

where, for each pair of indices  $ij$ , we have

- $f_{ij}(x) \in C^0(\mathbb{R}^d)$  (uniformly)

$$\begin{aligned} L_{ij}(u, x) = & \text{Tr}(A_{ij}(x)D^2u) + B_{ij}(x) \cdot \nabla u + C_{ij}(x)u \\ & + \int_{\mathbb{R}^d} (u(x+y) - u(x) - y \cdot \nabla u(x) \mathbb{1}_{B_1}(y)) \mu_{ij}(x, dy) \end{aligned}$$

## Structure from GCP

### Theorem (Guillen-Schwab 2016 and 2019)

Furthermore if  $I : C^{1,\gamma}(\mathbb{R}^d) \rightarrow C(\mathbb{R}^d)$  is Lipschitz and satisfies the GCP, then

$$\begin{aligned} L_{ij}(u, x) &= C_{ij}(x)u(x) + B_{ij}(x) \cdot \nabla u \\ &\quad + \int_{\mathbb{R}^d} u(x+y) - u(x) - \nabla u(x) \cdot y \mathbb{1}_{B_1(0)} \mu_{ij}(x, dy) \end{aligned}$$

and

$$\sup_{ij} \sup_x \int \min\{|y|^{1+\gamma}, 1\} \mu_{ij}(x, dy) < \infty.$$

## What is the connection?

Why are these three topics related?

A heuristic answer is that the D-to-N on half space is the  $-(-\Delta)^{1/2}$  operator.

So you can think after flattening the domain, the D-to-N is like a  $-(-\Delta)^{1/2}$  that depends in a nonlinear fashion on  $f$ .

# Analysis of Hele-Shaw

There is a more direct, but less obvious way to proceed. (Thanks to Hector!)

## Level-set formulation

First, let's remind ourselves of the level-set interpretation of Hele-Shaw flow

Let  $\Omega(t) \subset \mathbb{R}^N$  be a generic set which is said to have a boundary motion dictated by

$$\text{normal velocity}(x) = V(x)n(x) \quad \text{on } \partial\Omega(t),$$

where  $n(x)$  is the outward normal to  $\Omega(t)$  at  $x$ , and  $V(x)$  is a scalar.

Assume  $\Phi$  is some function so that

$$\Omega(t) = \{\Phi(\cdot, t) > 0\} \quad \text{and} \quad \partial\Omega(t) = \{\Phi(\cdot, t) = 0\}.$$

so

$$n(x) = \frac{-\nabla\Phi(x, t)}{|\nabla\Phi|}.$$

## Level-set formulation

Assume that  $\gamma : (0, 1) \rightarrow \mathbb{R}^M$  such that  $\forall t, \gamma(t) \in \partial\Omega(t)$ . Hence

$$0 = \partial_t(\Phi \circ \gamma) = \partial_t\Phi + \nabla\Phi \cdot \dot{\gamma},$$

and since we are assuming that  $(\dot{\gamma})_n = V$ ,

$$0 = \partial_t\Phi + (-n(x) |\nabla\Phi|) \cdot \dot{\gamma} = \partial_t\Phi - V |\nabla\Phi|,$$

so

$$\partial_t\Phi = V |\nabla\Phi|.$$



## Choices for $\Phi$

Now, let's go back to Hele-Shaw.

The first (most obvious) choice of  $\Phi$  is  $\Phi = U$ , which gives

$$\partial_t U_f = (\partial_n U_f) |\nabla U_f| \quad \text{on } \partial\{U_f(\cdot, t) > 0\}$$

The drawbacks are that:

- not obviously an equation for  $f$ , so no reduction of complexity,
- the domain is a manifold and is not fixed in time!

## Choices for $\Phi$

A different choice of  $\Phi$  is  $\Phi = x_{d+1} - f(x, t)$ , so that

$$\partial_t f(x, t) = (\partial_n U_f(x, f(x, t))) \sqrt{1 + |\nabla f(x, t)|^2} \quad \text{on } \mathbb{R}^d \times (0, T].$$

This is already an improvement, but still not perfect

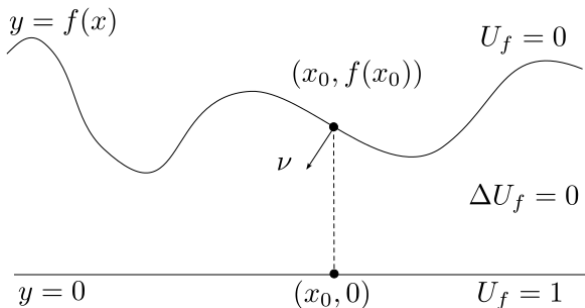
- CLOSER to an equation on only  $f$
- takes place on the nice, fixed domain,  $\mathbb{R}^d$ , so a reduction of variables!

## Hele-Shaw as a parabolic integro-differential equation

Again, **why** is this related to the **integro-differential equations**?!?!?

Focus on the following map (thanks, Hector!)

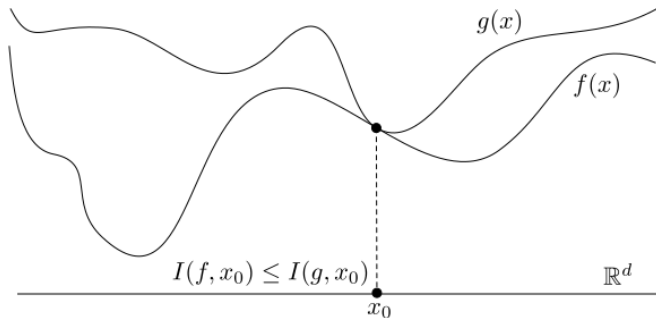
$$f \mapsto \partial_n U_f, \quad I(f, x) := \partial_n U_f(x, f(x)).$$



# Hele-Shaw as a parabolic integro-differential equation

## Lemma

The operator  $I(f, x) = \partial_n U_f(x, f(x))$  has the GCP.



## Hele-Shaw as a parabolic integro-differential equation

The other property of  $H(f) = I(f)\sqrt{1 + |\nabla f|^2}$  we need is the following.

Lemma (Chang Lara - Guillen - Schwab 2019)

For each  $\gamma \in (0, 1)$ ,  $H$  is Lipschitz continuous as a map from  $C_b^{1,\gamma}(\mathbb{R}^d)$  to  $C_b^0(\mathbb{R}^d)$ .

Hence... using the structure of GCP...

Theorem (Chang Lara - Guillen - Schwab 2019)

There exists a family,  $a^{ij}$ ,  $c^{ij}$ ,  $b^{ij}$ ,  $\mu^{ij}$ , so that  $f$  is the unique viscosity solution of

$$\partial_t f = \min_i \max_j a^{ij} + c^{ij} f(x) + b^{ij} \cdot \nabla f(x) + \int_{\mathbb{R}^d} \delta_h f(x) \mu^{ij}(dh).$$

Alert! min-max depends on the class of functions

place-holder, hopefully return to this later

## Regularity????

The previous theorem is only half of the battle!

### Theorem (Abedin-Schwab, forthcoming)

*Define*

$$\mathcal{K}(\delta, m, \rho) = \{f \in C^1 : \delta < f < m, |\nabla f| \leq m \text{ and } \nabla f \text{ is } \rho\text{-Dini}\}.$$

*H is Lipschitz on  $\mathcal{K}$ , the previous min-max remains intact, and with  $b^{ij}$ ,  $\mu^{ij}$  as above, for  $R_0$  depending on  $\delta, m, \rho$*

$$\mu^{ij}(dh) = K^{ij}(h)dh, \text{ and } \forall |h| \leq R_0, \quad c_1 |h|^{-d-1} \leq K^{ij}(h) \leq c_2 |h|^{-d-1},$$

*with*

$$\forall r \in (0, R_0), \quad \left| b^{ij} + \int_{B_{R_0} \setminus B_r} h K^{ij}(h) dh \right| \leq C$$

## Improvement of regularity

Consequence (via Chang Lara- Davila 2016)

### Theorem (Abedin-Schwab, forthcoming)

*There exists a universal  $\gamma$  so that if for all  $t$ ,  $\partial_t U \in C^0$ ,  $\partial\{U_f(\cdot, t)\} = \text{graph}(f(\cdot, t))$ , and  $f(\cdot, t) \in \mathcal{K}$ , then*

*$\partial\{U(\cdot, t) > 0\}$  is a  $C^{1,\gamma}$  graph.*



## Key Lemma: strict monotonicity

The main lemma is a strict monotonicity in direction of positive perturbations:

### Lemma

*If  $\text{support}(\psi) \subset B_{R_0}$  and  $|\psi(x)| \leq C|x|\rho(|x|)$ , then for all  $f \in \mathcal{K}$ ,*

$$tc_1 \int_{\mathbb{R}^d} \frac{\psi(y)}{|y|^{d+1}} dy \leq I(f + t\psi, 0) - I(f, 0) \leq tc_2 \int_{\mathbb{R}^d} \frac{\psi(y)}{|y|^{d+1}} dy.$$

# place-holder

Clarke differential versus finite dimensional approximation.  
Key step in min-max... the MVT. with which sets can you get the  
MVT?!?!?!?

## Some questions, next steps

- remove the *global* graph assumption... only locally a graph
- higher regularity
- other operators
- include gravity (see a recent work of Alarard - Meunier - Smets 2019 using water waves techniques)
- non-translation invariant situations
- other free boundary problems?

The End

Thanks!