

IV Knot theory

Rough idea: classify embeddings $Y \hookrightarrow X$ up to $\text{Aut}(X)$.

Since we will work in the smooth category, we first need some background on smooth manifolds.

1. Smooth manifolds

A $\overset{C^\infty}{\text{smooth}}$ map $f: U \rightarrow V$, where $U \subseteq \mathbb{R}^n$, $V \subseteq \mathbb{R}^m$ are open, is an

- immersion at $x_0 \in U$ if $D_{x_0} f \in \text{lin}(\mathbb{R}^n, \mathbb{R}^m)$ is injective ($\Rightarrow m \geq n$)
- submersion at $x_0 \in U$ if $D_{x_0} f$ is surjective ($\Rightarrow m \leq n$)

(\Leftarrow immersion/submersion if prop. holds at all points)

- diffeomorphism if f bijective & f^{-1} smooth

(chain rule) $\Rightarrow f$ immersion & submersion $\Rightarrow m = n$

A diffeomorphism is a "smooth coordinate change".

Non-Ex $x \mapsto x^3$ is smooth, bijective, but not a diffeo.

Thm. 15 (Implicit function theorem) Let $f: U \rightarrow \mathbb{R}^m$ be a smooth function, fix $x_0 \in U$, and write $y_0 := f(x_0)$. If f is

- a submersion at x_0 , then \exists neighbourhoods $U_0 \subseteq U$ of x_0 and

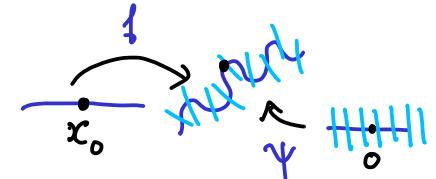
$V_0 \subseteq \mathbb{R}^m$ of $f(x_0)$, diffeomorphisms $\psi: \mathbb{R}^n \rightarrow U_0$, $\varphi: \mathbb{R}^m \rightarrow V_0$

$$\begin{array}{ccc} 0 & \mapsto & x_0 \\ 0 & \mapsto & y_0 \end{array}$$

s.t. $\boxed{\psi^{-1} \circ f \circ \varphi(x_1, \dots, x_n) = (x_1, \dots, x_m)} \quad (m \leq n).$

- an immersion at x_0 , then similarly \exists nbhds & diff's

s.t. $\boxed{\psi^{-1} \circ f \circ \varphi(x_1, \dots, x_n) = (x_1, \dots, x_n, 0, \dots, 0)}.$



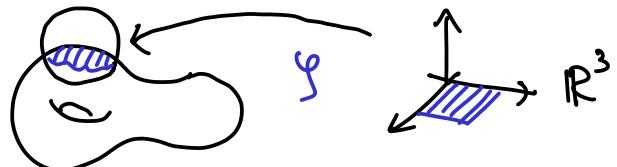
Obs: in particular if $f: U \rightarrow V$ smooth, bij., $D_x f \in \text{GL}_n$ (imm. & subm.)

$\Rightarrow f$ is locally a diffeomorphism (e.g. the $\mathbb{C}^* \rightarrow \mathbb{C}^*$
k-fold cover $z \mapsto z^k$)

Def • An embedded submanifold (of \mathbb{R}^n) is a subset $M \subseteq \mathbb{R}^n$ for which every $p \in M$ has a nbhd. $U \subseteq \mathbb{R}^n$ s.t.

\exists diffeomorphism $\psi: \mathbb{R}^n \rightarrow U$ where $\psi^{-1}(M \cap U) = \mathbb{R}^m \times \{0\} \subseteq \mathbb{R}^n$.

- A map $f: M \rightarrow N$ between embedded submanifolds is called smooth if it is the restriction of some smooth map defined on an open nbhd. of $M \subseteq \mathbb{R}^n$.



The restriction $g|_{\mathbb{R}^m \times \{0\}} : \mathbb{R}^m \hookrightarrow M$ is called a local parametrisation, which means it is an injective immersion with image being an open subset of M .

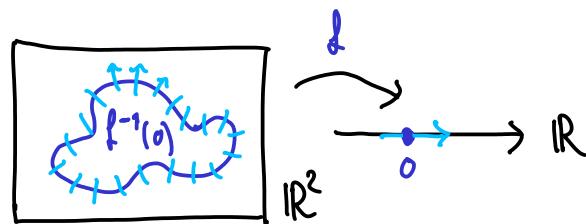
In particular: smooth submanifolds are topological manifolds.
(metric topology & 2nd countability inherited from \mathbb{R}^n)

A smooth map $f : M \rightarrow N$ is called an immersion/submersion if the same is true for the maps:

$$g_N^{-1} \circ f \circ g_M : \mathbb{R}^{\dim M} \rightarrow \mathbb{R}^{\dim N}$$

expressed w.r.t. local parametrisations.

Exercise 17.) Show that the preimage $f^{-1}(pt) \subseteq \mathbb{R}^n$ of any smooth map $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ which is a submersion at all points in $f^{-1}(pt)$ is a submanifold of dimension $n-m$.



- Ex
- $S^n \subseteq \mathbb{R}^{n+1}$ smooth n -dim submfd.
 - $S^{n_1} \times S^{n_2} \times \dots \times S^{n_m} \subseteq \mathbb{R}^{n_1 + \dots + n_m + m}$

A smooth map $f: M \rightarrow N$ with a smooth inverse is called a diffeomorphism.

⚠ The map $f: M \rightarrow N$ is not necessarily the restriction of a global diffeomorphism $\mathbb{R}^n \xrightarrow{\cong} \mathbb{R}^m$

E.g. $S^n \times \{0\} \subseteq \mathbb{R}^{n+2}$ is diffeom. to $S^n \subseteq \mathbb{R}^{n+1}$

Prop 16. If M is a compact (sub)manifold and $f: M \hookrightarrow \mathbb{R}^n$ is an injective smooth immersion, then the image $f(M) \subseteq \mathbb{R}^n$ is a smooth (sub)manifold and $f: M \rightarrow f(M)$ is a diffeomorphism.

Proof The local parametrisations of M give rise to local parametrisations $f \circ g: \mathbb{R}^{\dim M} \hookrightarrow f(M) \subseteq \mathbb{R}^n$ of the image.

Goal: extend $f \circ g$ to a diffeomorphism

$$\Phi: \mathbb{R}^{\dim M} \times \mathbb{R}^{n-\dim M} \xrightarrow{\quad} U, \quad \Phi^{-1}(f(M)) = \mathbb{R}^{\dim M} \times \{0\} \quad (*)$$

M cpt $\Rightarrow f(M)$ cpt & $f|_M : M \rightarrow f(M)$ homeo! (gen. fact)
smoothness of f^{-1} can be seen in loc. coord's.

The sought extensions Φ exist as a consequence of the implicit function theorem (Thm. 15).

For (*) we need to use compactness. Assume the

produced Φ satisfy $\Phi^{-1}(f(M)) = \mathbb{R}^{\dim M} \times \{0\} \cup A$, $A \neq \emptyset$.

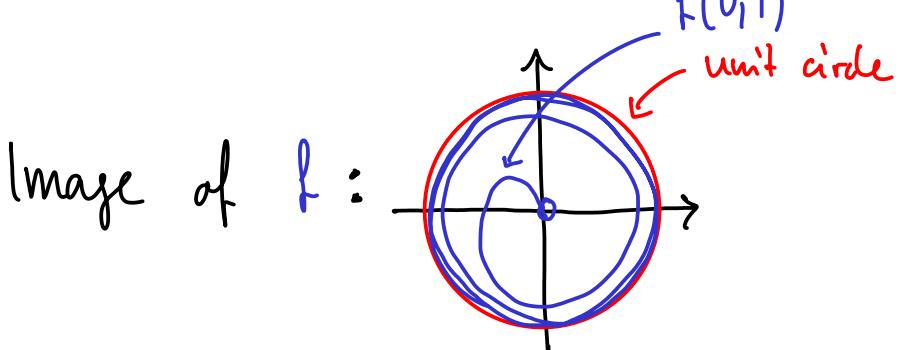
- $A \subseteq \mathbb{R}^n \setminus \mathbb{R}^{\dim M} \times \{0\}$ closed \Rightarrow shrink domain & target, done!
- otherwise, use compactness of M to show that f is not injective \Rightarrow contradiction \therefore . \square

$A \subseteq f(M)$
 $\mathbb{R}^{\dim M} \times \{0\} \subseteq f(M)$
pts converging to double pt.

non-compact 1-dim mfld.

Non-Ex $f: \overbrace{S^1 \sqcup (0,1)}^{\text{non-compact 1-dim mfld.}} \hookrightarrow \mathbb{R}^2$ which is the canonical

inclusion on the S^1 factor, while $f|_{(0,1)}(x) = x \cdot e^{i \frac{1}{1-x}}$



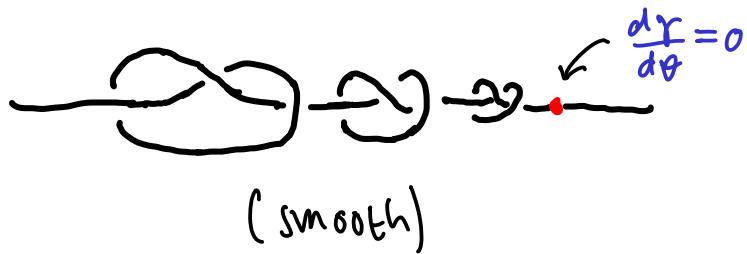
A (one-dim) knot is a closed one-dim submanifold
 conn., comp.

$K \subseteq \mathbb{R}^3$ (m nr. of) (m component)
 A disjoint union of \downarrow knots is called a \downarrow link.

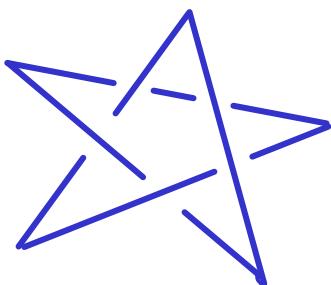
A knot can be obtained as the image of a smooth inj. immersion

$$\gamma: \frac{\mathbb{R}}{2\pi\mathbb{Z}} \xrightarrow{\cong} S^1, \quad \frac{d\gamma}{d\theta} \neq 0 \quad (\text{immersion})$$

immersion is needed to rule out "wild knots"



Alternative model: Piecewise linear embeddings



(up to suitable equivalence)

Isotopies

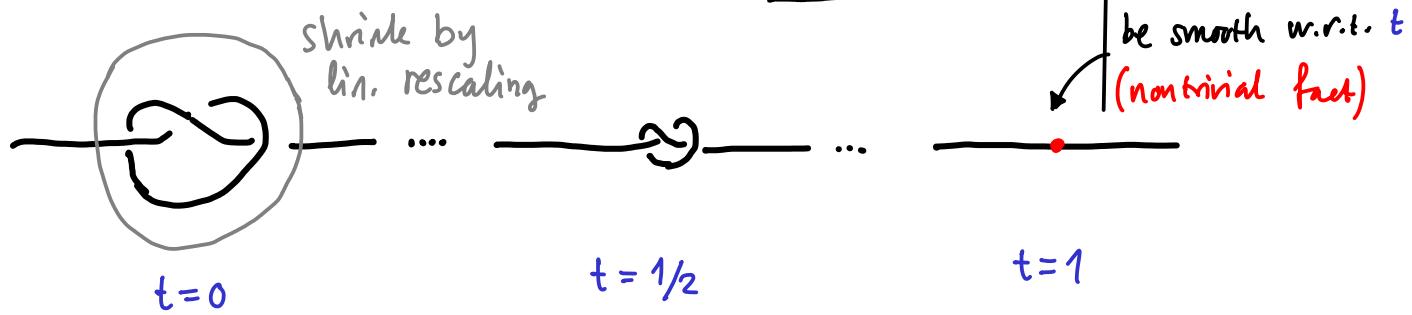
In smooth knot theory one is typically interested in (smooth) submanifolds up to (smooth) isotopy, i.e.

$$\varphi: \underbrace{[0,1] \times M}_{\text{manifold}} \rightarrow \mathbb{R}^n \quad \text{smooth} \quad (M \text{ compact})$$

$$\varphi_t = \varphi(t, \cdot): \{t\} \times M \hookrightarrow \mathbb{R}^n \quad \text{injective immersion} \quad \forall t \in [0,1]$$

(Prop. 16) $\Rightarrow \varphi_t(M)$ "path" of submanifolds

Smoothness in the t -variable is crucial



Thm 17. (Isotopy extension) Any smooth isotopy

$\varphi_t: M \hookrightarrow \mathbb{R}^n$ of a compact manifold is of the form

$\varphi_t = \Phi_t \circ \varphi_0$ for a compactly supported isotopy of the

ambient \mathbb{R}^n , i.e. $\Phi_t: \mathbb{R}^n \rightarrow \mathbb{R}^n$ diffeo's smoothly dep. on $t \in [0,1]$.

$$\Phi_0 = \text{id}_{\mathbb{R}^n}$$

$$\Phi_t = \text{id}_{\mathbb{R}^n} \quad \text{outside a fixed compact subset}$$