

Thm. 25 1.) Connected sum is a well-defined operation on smooth isotopy classes of oriented knots.

2.) Conn. sum is associative & commutative

3.) $K \# \text{unknot} \stackrel{(\text{iso.})}{=} K$

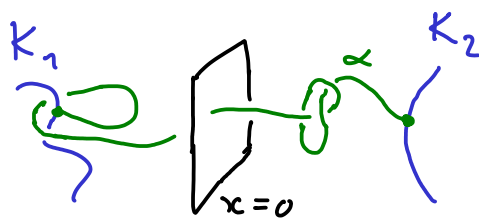
4.) $g(K_1 \# K_2) = g(K_1) + g(K_2)$ $\left(\Rightarrow \text{infinitely many iso. classes of knots!} \right)$

Def A knot K is prime if $K = K_1 \# K_2$

\Rightarrow one of $K_i, i=1, 2$, is the unknot.

Ex The trefoil is prime by Thm. 25 (4.)

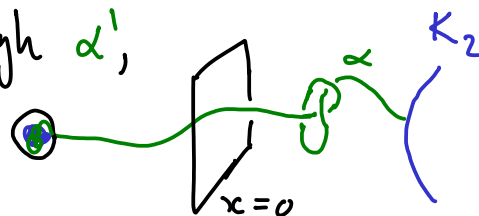
Proof of Thm. 25



1.) Claim $K_1 \cup \alpha \cup K_2$ is ambient isotopic to $K_1 \cup \alpha' \cup K_2$ whenever α, α' are two paths in the construction.

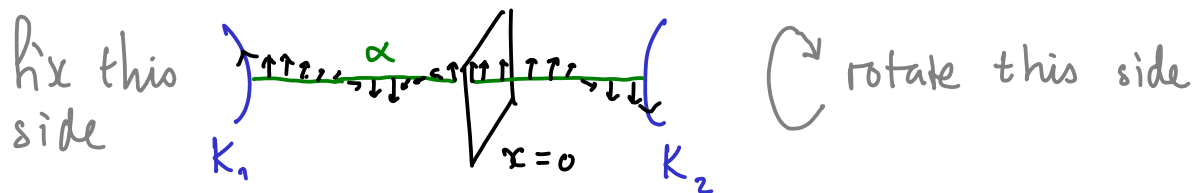
Pf. Near endpoints: can be made to coincide "by hand".

To "undo the mess" in $\{x > 0\}$: Shrink $\{x < 0\}$ into a small ball and "thread" through α' , and back through α .



Similarly in $\{x < 0\}$.

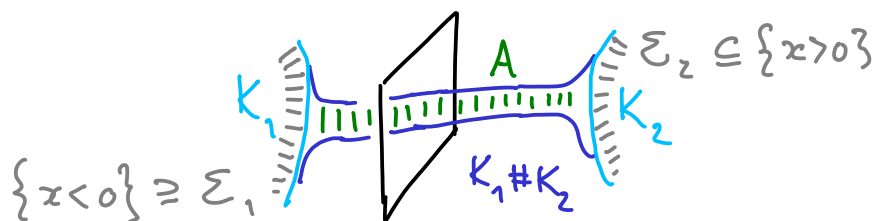
The additional choice of twisting along α in the construction can then be undone by an ambient rotation in $\{x > 0\}$



2.) Exercise 27.)

3.) Obviously in view of (1.)

4.) Look near $\{x=0\}$. Using (1), we may assume



$g(K_1 \# K_2) \leq g(K_1) + g(K_2)$ holds since we can

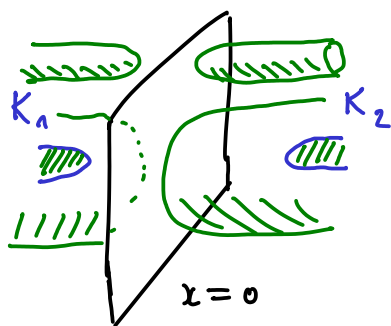
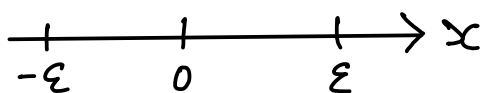
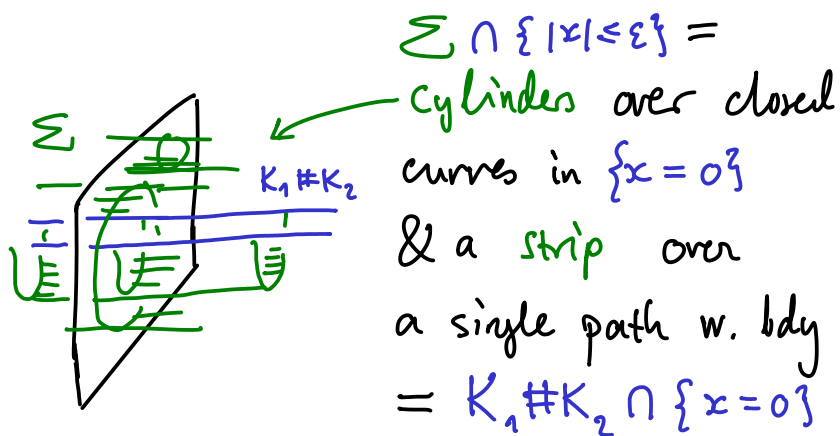
glue Seifert surfaces for K_1 & K_2 by adding the

band A . (Obs: $\mathbb{R}^3 \setminus (\Sigma_1 \cup \Sigma_2)$ is path connected,

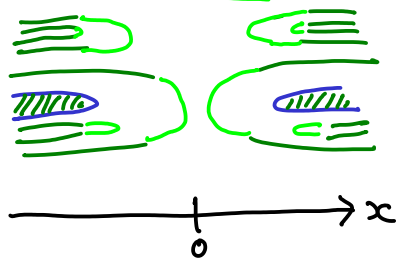
by (1.) we can assume $\alpha \in \mathbb{R}^3 \setminus (\Sigma_1 \cup \Sigma_2 \setminus (K_1 \cup K_2))$.)

The opposite inequality is seen by splitting any Seifert surface Σ of $K_1 \# K_2$ along $\{x=0\}$.

After a generic perturbation of Σ we may assume that it takes the following form in $[-\varepsilon, \varepsilon] \times \mathbb{R} \times \mathbb{R} \subseteq \mathbb{R}^3$:



Cut open cylinders along $\{x=0\}$ and add **discs**



Resulting surface does not intersect $\{x=0\}$ & has bdy $= K_1 \cup K_2$.

Throw away closed components.




Compute χ (c.f. Exc. (25.)) to show that total genus cannot increase! \square

6. The Alexander polynomial

Intersection form

For any oriented surface Σ we have an "intersection form" defined on curves in the following manner.

Let $x, y \subseteq \Sigma$ be two closed oriented curves (here: immersed)

$$x \cdot y \stackrel{\text{def}}{=} \sum_N 1 - \sum_N 1 \in \mathbb{Z}$$


after a small generic perturbation (well-def & indep. of perturbation)

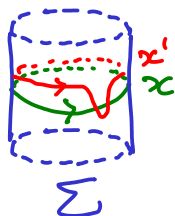
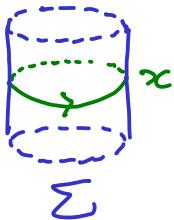
\Rightarrow " \cdot " is "linear"
 "skew symmetric"
 $\Rightarrow x \cdot x = 0$.

$$(-1)^i x \cdot (-1)^j y = (-1)^{i+j} x \cdot y$$

$$x \cdot y = -y \cdot x$$

change of orientation

Geometric computation (x embedded)



$$x \cdot x \stackrel{\text{def}}{=} x \cdot x' = 0$$

nbhd of $x \cong$ annulus

(two-sided since Σ is orientable, so not a Klein bottle)

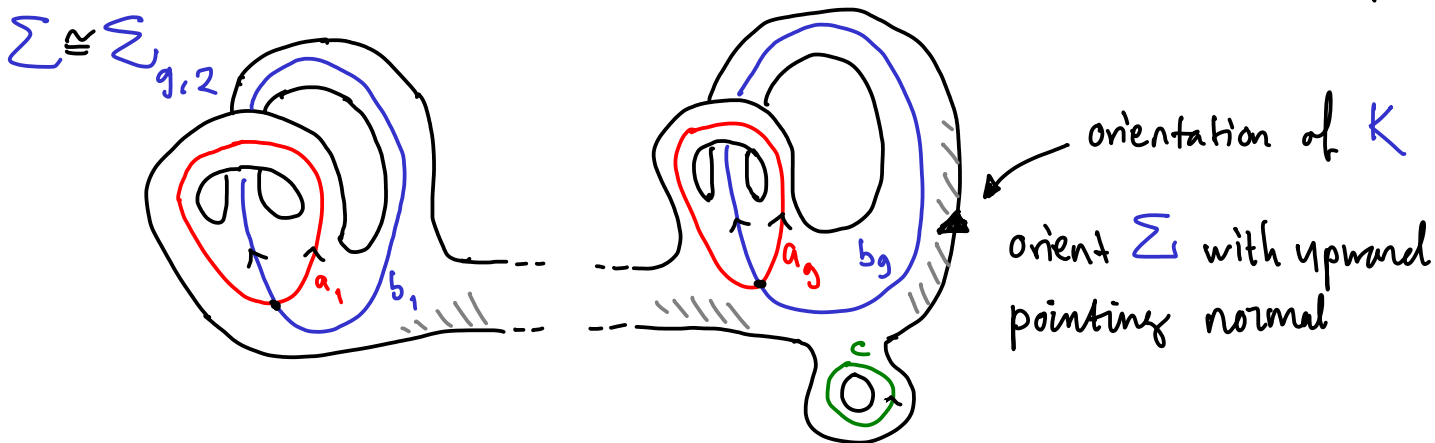
Fact $\cup \cdot \cup: H_1(\Sigma) \times H_1(\Sigma) \rightarrow \mathbb{Z}$ is well-def, \mathbb{Z} -bilinear, & skew symmetric.

The Seifert matrix

Let $\Sigma \subseteq \mathbb{R}^3$ be a Seifert surface for $\partial\Sigma = L$.

(Recall: connected, orientable compact)

↑
oriented \Rightarrow
orientation of Σ



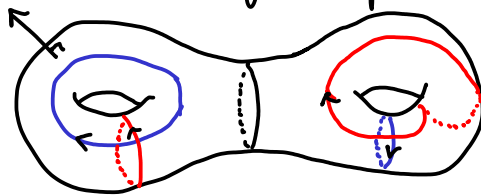
The oriented embedded curves $a_i, b_i, i=1, \dots, g$ satisfy the intersection properties

$$a_i \cdot b_j = \begin{cases} 1, & i=j, \\ 0, & i \neq j. \end{cases}$$

$$(a_i \cdot a_i = b_i \cdot b_i = 0 \text{ always true})$$

Fact: Any collection of closed curves a_i, b_i satisfying the above is a basis of $H_1(\Sigma_{g,k}) \cong \mathbb{Z}^{2g}$, $k=0$ or 1 .

In general $H_1(\Sigma_{g,k}) \cong \mathbb{Z}^{2g+k-1}$, where the additional $k-1$ curves can be taken among the k bdy. components (on which " \cdot " is trivial)



Pick a basis of curves as above and

write $e_1 = a_1, e_2 = b_1, e_3 = a_3, \dots, e_{2g-1} = a_g, e_{2g} = b_g, \overbrace{e_{2g+1} = c_1, \dots}^{k-1 \text{ bdy comp.}}$

The Seifert matrix induced by Σ is

$V \in \text{Mat}_{2g, 2g}(\mathbb{Z})$ with entries

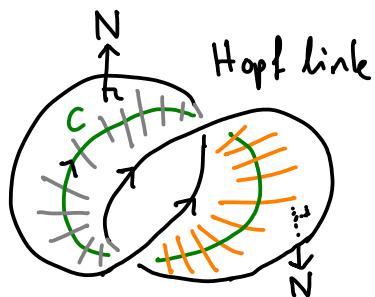
$$v_{ij} = \text{lk}(e_i, e_j^\#)$$

row
pushoff of e_j
along normal of Σ .

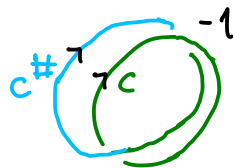
col.

V is invariant / change of basis & certain stabilisations, but we will not focus V itself here.

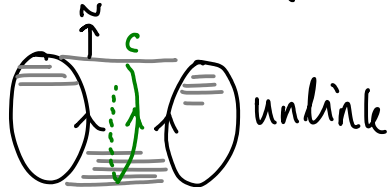
Σ_x



$$V = [\text{lk}(c, c^\#)] = [-1]$$

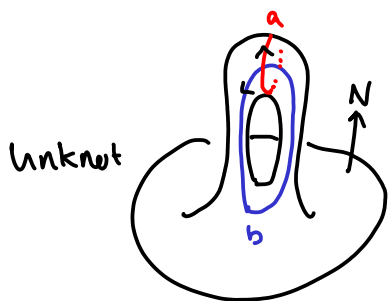


$\Sigma = \text{annulus (twisted)}$



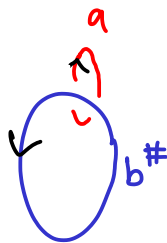
$$V = [0]$$

$\Sigma = \text{annulus (untwisted)}$

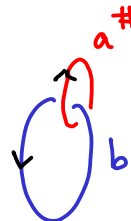


$$V = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$\text{lk}(a, b^\#)$



$\text{lk}(b, a^\#)$



The Alexander polynomial is the Laurent polynomial

$$\Delta_L(t) := t^N \cdot \det(tV - V^t) \in \mathbb{Z}[t, t^{-1}]$$

$N \in \mathbb{Z}$ s.t.

- honest polynomial
- not divisible by t (unless zero)

(\triangle there are different conventions)

We compute $\Delta_{\emptyset\emptyset}(t) = 0$, $\Delta_{\emptyset}(t) = t - 1$,

$$\Delta_0(t) = t^{-1} \cdot \det \begin{bmatrix} 0 & -1 \\ t & 0 \end{bmatrix} = 1.$$

Clearly

$$\Delta_{K_1 \# K_2}(t) = \Delta_{K_1}(t) \cdot \Delta_{K_2}(t)$$

Exercise 28.) Show that (1) $\pm t^{\deg \Delta} \Delta(t^{-1}) = \Delta(t)$

$$(2) \Delta_{\text{Knot}}(1) = \pm 1$$

Exercise 29.) Calculate $\Delta_{\text{G}}(t) = 1 - t + t^2$

Thm. 26. (Alexander, '28) The Alexander polynomial

is an isotopy invariant of links.