

## Modal Logic and Computation Tree Logic

The BONUS PROBLEMS are marked (+) below. Solutions of these are to be handed in at the latest on 7 December. Maximum bonus for this set of problems is 2.5%. LCS below denotes the course book *Logic in Computer Science* by M. Huth and M. Ryan.

1. Suppose the intended meaning of  $\Box\phi$  is 'Agent A knows  $\phi$ '. Formalise the following statements in modal logic:
  - (a) If  $\phi$  is true, then it is consistent with what A knows, that A knows it.
  - (b) If it is consistent with what A knows that  $\phi$ , and it is consistent with what A knows that  $\psi$ , then it is consistent with what A knows that  $\phi \wedge \psi$ .
  - (c) If A knows  $\phi$ , then it is consistent with what A knows that  $\phi$ .
  - (d) If it is consistent with what A knows that it is consistent with what A knows that  $\phi$ , then it is consistent with what A knows that  $\phi$ .

Which of these statements seems plausible principles concerning knowledge and consistency.

2. Show that the following formulas are valid (with respect to the class of all frames)
  - (a)  $\Diamond\phi \leftrightarrow \neg\Box\neg\phi$ ,
  - (b)  $\Box(\phi \wedge \psi) \leftrightarrow \Box\phi \wedge \Box\psi$ ,
  - (c)  $\Diamond(\phi \vee \psi) \leftrightarrow \Diamond\phi \vee \Diamond\psi$ .
3. Consider the basic temporal language and the following frames  $(\mathbb{Z}, <)$ ,  $(\mathbb{Q}, <)$  and  $(\mathbb{R}, <)$ , where  $<$ , in each case, is the usual less-than relation. Which of the following formulas are valid on these frames?
  - (a)  $GGp \rightarrow p$ ,
  - (b)  $(p \wedge Hp) \rightarrow FHp$ .
4. Show that the following formulas are non-valid by constructing a counterexample in each case:

- (a)  $\Box\perp$ ,
- (b)  $\Diamond p \rightarrow \Box p$ ,
- (c)  $p \rightarrow \Box\Diamond p$ ,
- (d)  $\Diamond\Box p \rightarrow \Box\Diamond p$ ,
- (e)  $\Box p \rightarrow p$ .

5. (+) Show the following

(a) Frame-validity of B:  $\phi \rightarrow \Box\Diamond\phi$  corresponds to symmetry of  $R$ .

(b) Frame-validity of D:  $\Box\phi \rightarrow \Diamond\phi$  corresponds to  $R$  being serial.

6. Let  $\mathbf{F}$  be a class of frames. Show that  $\Lambda_{\mathbf{F}} = \{\varphi \mid \mathcal{F} \models \varphi \text{ for all } \mathcal{F} \in \mathbf{F}\}$  is a normal modal logic.

7. Consider a modal language with two boxes [1] and [2]. Show that  $p \rightarrow [2]\langle 1\rangle p$  is valid on precisely those frames for the language that satisfy the condition

$$\forall xy(xR_2y \rightarrow yR_1x).$$

What sort of frames does  $p \rightarrow [1]\langle 1\rangle p$  define?

8. Consider a language with three boxes [1], [2] and [3]. Show that the modal formula  $\langle 3\rangle p \leftrightarrow \langle 1\rangle\langle 2\rangle p$  is valid on a frame for this language if and only if the frame satisfies the condition

$$\forall xy(xR_3y \leftrightarrow \exists z(xR_1z \wedge zR_2y)).$$

9. (+) Consider a language with two boxes [1] and [2]. Prove that the class of frames in which  $R_1 = R_2^*$ , where  $R_2^*$  is the reflexive transitive closure of  $R_2$ , is defined by the formulas

$$(a) \langle 1\rangle p \rightarrow (p \vee \langle 1\rangle(\neg p \wedge \langle 2\rangle p)),$$

$$(b) \langle 1\rangle p \leftrightarrow (p \vee \langle 2\rangle\langle 1\rangle p).$$

10. Suppose  $\mathcal{T} = (T, <)$  is a bidirectional frame (where we write  $y < x$  instead of  $x \check{<} y$ ) such that  $<$  is transitive, irreflexive and satisfies  $\forall xy(x < y \vee x = y \vee y < x)$ . Show that

$$\mathcal{T} \models \{G(Gp \rightarrow p) \rightarrow Gp, H(Hp \rightarrow p) \rightarrow Hp\}$$

implies that  $\mathcal{T}$  is finite.

11. Show that Grzegorzczk's formula

$$\Box(\Box(p \rightarrow \Box p) \rightarrow p) \rightarrow p$$

characterizes the class of frames  $\mathcal{F} = (W, R)$  satisfying

- (i)  $R$  is reflexive,
  - (ii)  $R$  is transitive,
  - (iii) there are no infinite paths  $x_0Rx_1Rx_2R\dots$  such that for all  $i$ ,  $x_i \neq x_{i+1}$ .
12. (+) Exercise 3.4.6 (a) and (b) (only CTL formulas) in Chapter 3 of LCS
  13. Exercise 3.4.7 (f)-(h) in Chapter 3 of LCS
  14. (+) Exercise 3.4.8 in Chapter 3 of LCS
  15. (+) Exercise 3.4.10 (c)-(g) in Chapter 3 of LCS

Some of the exercises are taken from the book *Modal Logic* by Patrick Blackburn, Maarten de Rijke and Yde Venema, which is a very good reference for Modal Logic.