

## DIFFERENTIAL GEOMETRY

### PROBLEM 1-5

1. Show that the curvature of a plane curve is in general given by the formula

$$\kappa(t) = \frac{\det(\dot{c}(t), \ddot{c}(t))}{|\dot{c}(t)|^3}.$$

2. Show that the curvature and torsion of a space curve are in general given by the formulae

$$\kappa(t) = \frac{|\dot{c}(t) \times \ddot{c}(t)|}{|\dot{c}(t)|^3},$$
$$\tau(t) = \frac{\det(\dot{c}(t), \ddot{c}(t), c(t))}{|\dot{c}(t) \times \ddot{c}(t)|^2},$$

where  $x \times y$  is the vector product in  $R^3$ .

3. Let  $c(t)$  be a curve in  $R^n$  parametrized by arc length with the property that  $|c(t)|^2$  has a local maximum at  $t_0$ . Let  $p_0 = c(t_0)$  and  $\rho^2 = |p_0|^2$ . Show that

$$\kappa(t_0) \geq \frac{1}{\rho}$$

where  $\kappa(t_0) = |\ddot{c}(t_0)|$  (which is equal to the first curvature of  $c(t)$  at  $t_0$  if it is defined).

4. Let  $A, B, C, D, E, G$  be constants such that

$$AD + BE + CG \neq 0.$$

Consider the curves  $c(t) = (x(t), y(t), z(t)) \in R^3$  whose tangent vectors at each point  $P = (x, y, z)$  in space are in the plane  $L_P$  through  $P$  whose normal is

$$(Bz - Cy + D, Cx - Az + E, Ay - Bx + G).$$

It is clear that such curves satisfy

$$(Bz(t) - Cy(t) + D)\dot{x}(t) + (Cx(t) - Az(t) + E)\dot{y}(t) + (Ay(t) - Bx(t) + G)\dot{z}(t) = 0.$$

Let  $c(t)$  be a curve which satisfies such a condition and assume that  $\dot{c}(t), \ddot{c}(t)$  are linearly independent at  $P$ . Let  $\tau$  be the torsion of the curve at  $P = (x, y, z)$ .

a) Show that  $L_P$  is the osculating plane of the curve at  $P$ .

b) Show that  $\tau$  at  $P$  satisfies the formula

$$\tau = \frac{-(AD + BE + CG)}{(Bz - Cy + D)^2 + (Cx - Az + E)^2 + (Ay - Bx + G)^2}.$$

5. Let  $c(t)$  be a curve in  $R^3$  parametrized by arc length and let  $t_0 = 0 \in I$ . Let the Frenet-frame at  $c(0)$  be  $e_i(0) = e_i$  and let  $\kappa(0) = \kappa_0, \tau(0) = \tau_0$ . We then have the following well known series expansion for  $t$  close to 0

$$c(t) - c(0) = te_1 + \frac{1}{2}\kappa_0 t^2 e_2 + \frac{1}{6}\kappa_0 \tau_0 t^3 e_3 + o(t^3).$$

The projections of the curve in a small neighbourhood of  $c(0)$  in the planes of the Frenet-frame at that point are therefore approximated by the following curves:

a) the projection onto the  $(e_1, e_3)$ -plane, the rectifying plane, is described by the cubical parabola

$$x = t, \quad y = 0, \quad z = \frac{1}{6}\kappa_0 \tau_0 t^3;$$

b) the projection onto the  $(e_2, e_3)$ -plane, the normal plane, is described by the semi-cubical parabola with a cusp at origo

$$x = 0, \quad y = \frac{1}{2}\kappa_0 t^2, \quad z = \frac{1}{6}\kappa_0 \tau_0 t^3;$$

c) the projection onto the  $(e_1, e_2)$ -plane, the osculating plane, is described by the parabola

$$x = t, \quad y = \frac{1}{2}\kappa_0 t^2, \quad z = 0.$$

i) Draw these projektions and their orientations in the case  $\tau_0 > 0$  and  $\tau_0 < 0$ .

ii) We shall now study what the curve looks like along the negative  $e_1$ -axis if we raise or lower our eyes somewhat above or under the osculating plane. This means that we shall find the projection of the curve in a  $(f_2, f_3)$ -plane where the  $ON$ -system  $(f_1, f_2, f_3)$  is created from the system  $(e_1, e_2, e_3)$  by letting the  $e_1, e_3$ -plane rotate a small angle  $\alpha$  ( $-\varepsilon < \alpha < \varepsilon$ ) with the  $e_2$ -axis as axis of rotation. Derive the analytical expression of the projection and draw pictures of how it looks for different values of  $\alpha$  in the cases  $\tau_0 > 0$  and  $\tau_0 < 0$ .