

Recall that a function $f: M \rightarrow \mathbb{R}^m$ is smooth if it is the restriction of a smooth function defined on some open nbhd of $M \subseteq \mathbb{R}^n$ by our definition. The following local characterisation is crucial (& used implicitly in the proof of Prop. 16)

Lem. 18 Let $M \subseteq \mathbb{R}^n$ be a submanifold. Any function $f: M \rightarrow \mathbb{R}^N$ which satisfies the property that $\text{fog}: \mathbb{R}^{\dim M} \rightarrow \mathbb{R}^N$ is smooth for any local parametrisation $g: \mathbb{R}^{\dim M} \hookrightarrow M \subseteq \mathbb{R}^n$ is the restriction of a ^{non-unique!} smooth function $F: \mathbb{R}^n \rightarrow \mathbb{R}^N$.

Proof Since g can be extended to a diffeomorphism

$$\Phi: \mathbb{R}^{\dim M} \times \mathbb{R}^{n-\dim M} \xrightarrow{\quad \downarrow \quad} U \subseteq \mathbb{R}^n, \quad \Phi^{-1}(M \cap U) = \mathbb{R}^{\dim M} \times \{0\}$$

$$\begin{matrix} \bar{x}_1 \\ \bar{x}_2 \end{matrix}$$

such an extension can be found in U , e.g. $F_U(\bar{x}_1, \bar{x}_2) = f(\bar{x}_1)$.

In this manner we may assume that we have a covering $\{U_i\}$ of \mathbb{R}^n by open subsets, together w. smooth functions

$F_i: U_i \rightarrow \mathbb{R}^N$ that satisfy $F_i|_{M \cap U_i} = f$.

These functions can now be patched together to form the globally def. function $F: \mathbb{R}^n \rightarrow \mathbb{R}^N$ by the following "partition of unity" argument:

1.) "Refine" the cover by constructing a cover by

open balls $\{B_{r_i}(p_i)\}$, $r_i > 0$, $p_i \in \mathbb{R}^n$, s.t.

- $\overline{B_{r_i}(p_i)} \subseteq U_{\alpha(i)}$ and "paracompactness"

which is locally finite, i.e. for each fixed i :

- $B_{r_i}(p_i) \cap B_{r_j}(p_j) = \emptyset$ for all but finitely many j .

2.) Consider smooth functions $\sigma_i: \mathbb{R}^n \rightarrow [0, +\infty)$

which satisfy $\sigma_i^{-1}(0) = \mathbb{R}^n \setminus B_{r_i}(p_i)$.

3.) Take $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ to be

$$F(\bar{x}) = \frac{\sum_i \sigma_i(\bar{x}) \cdot F_{\alpha(i)}(\bar{x})}{\sum_i \sigma_i(\bar{x})}$$

sums are infinite, but
still make sense by (1.)

\leftarrow non-zero term \exists by (2.)

Obs: $\bar{x} \in M \Rightarrow F(\bar{x}) = \frac{\sum_i \sigma_i(\bar{x}) \cdot f(\bar{x})}{\sum_i \sigma_i(\bar{x})} = f(\bar{x}) \quad \square$

Proof (Isotopy extension theorem)

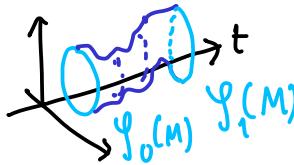
For convenience, assume $\varphi: \mathbb{R}_t \times M \rightarrow \mathbb{R}^n$.

Prop. 16 $\Rightarrow \varphi_t(M) \subseteq \mathbb{R}^n$ submanifold for each t

check
by hand

& $\varphi_t: M \rightarrow \varphi_t(M)$ diffeomorphism

$\Rightarrow \text{image}((t, \varphi_t): \mathbb{R} \times M \rightarrow \mathbb{R} \times \mathbb{R}^n) = \{(t, x); x = \varphi_t(y), y \in M\}$ is a
called the trace of φ_t submanifold

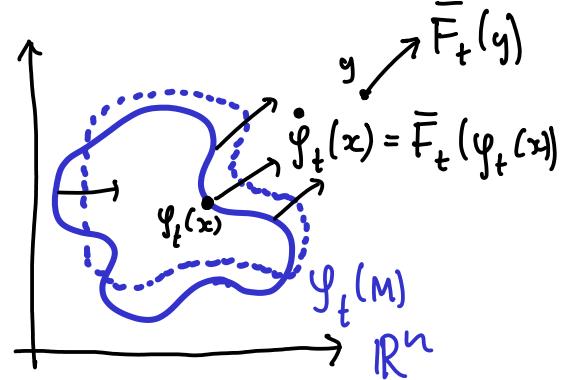


& $(t, \varphi_t): \mathbb{R} \times M \rightarrow \mathbb{R} \times \mathbb{R}^n$ is a diffeomorphism.

Hence, the smooth function

$\mathbb{R} \times \mathbb{R}^m$
VI submt.

$\frac{\partial}{\partial t} \varphi: \mathbb{R}_t \times M \rightarrow \mathbb{R}^n$



gives rise to the smooth function

$\frac{\partial}{\partial t} \varphi \circ (t, \varphi_t)^{-1}: \text{trace} \rightarrow \mathbb{R}^n$
 $\subseteq \mathbb{R} \times \mathbb{R}^n$

Basically, Lem. 18 is responsible for ensuring that $(t, \varphi_t)^{-1}$ has a smooth extension.

In particular, \exists smooth extension \bar{F} to $\mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$

i.e. a t -dependent vector field on \mathbb{R}^n which may be assumed to vanish outside of some compact subset.

We write $\bar{F}_t : \mathbb{R}^n \rightarrow \mathbb{R}^n$, which by construction satisfies
 \downarrow
smooth in "t" as well

$$(*) \quad \frac{\partial}{\partial t} \psi_t(x_0) = \bar{F}_t(\psi_t(x_0)) \quad \text{for all } x_0 \in M.$$

The existence of solution $\Phi_t(y) \in \mathbb{R}^n$ to the ODE

$$\begin{cases} \frac{d}{dt} \Phi_t(y) = \bar{F}_t(\Phi_t(y)) & (\text{ODE}) \\ \Phi_0(y) = y & (\text{IC}) \end{cases}$$

together with smooth dependence on the initial conditions (IC)
gives the sought ambient isotopy

$$\Phi : [0, 1] \times \mathbb{R}^n \longrightarrow \mathbb{R}^n$$

ψ_t y smooth

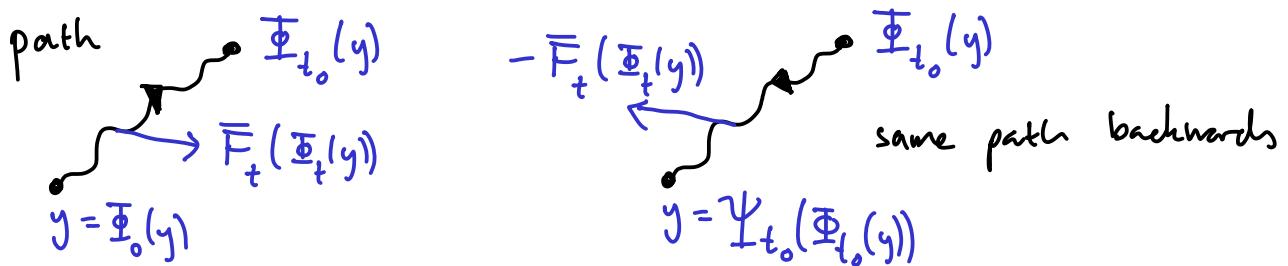
Indeed, uniqueness & (*) $\Rightarrow \Phi_t \circ \varphi_0 = \varphi_t$

- Each Φ_t is a compactly supported since $\Phi_0 = \text{id}_{\mathbb{R}^n}$ & $\frac{d}{dt} \Phi_t = 0$ outside a cpt subset.

- Φ_{t_0} is a diffeomorphism for all $t_0 \in [0, 1]$ since the solution $\Psi_t(y)$ of the "backwards flow":

$$\begin{cases} \frac{d}{dt} \Psi_t(y) = -\bar{F}_{t_0-t}(\Psi_t(y)) \\ \Psi_0(y) = y \end{cases}$$

satisfies $\Psi_{t_0} \circ \Phi_{t_0} = \text{Id}_{\mathbb{R}^n}$ by uniqueness of sol.



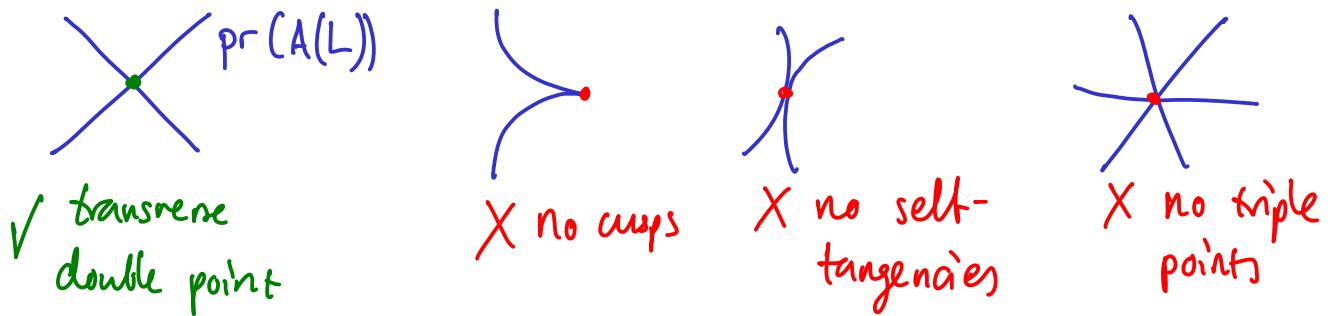
□

2. Knot projections & Knot diagrams

Goal: reduce the isotopy problem to "combinatorics".

Consider the orthogonal projection $\text{pr}: \mathbb{R}_{x,y,z,\dots}^{2+k} \rightarrow \mathbb{R}_{z,y}^2$

Thm. 19 (Jet transversality) For a link $L \subseteq \mathbb{R}^{2+k}$, any generic $A \in SO(2+k)$ (i.e. $A \in U_L \subseteq SO(2+k)$, U open & dense) has the property that $\text{pr}(A(L))$ is an immersion with only transverse double points.

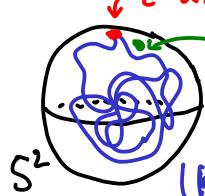


Idea Parametrise $K \subseteq \mathbb{R}^{2+k}$ by an immersion

$$\gamma: S^1 = \mathbb{R}/2\pi\mathbb{Z} \rightarrow K \subseteq \mathbb{R}^{2+k}$$

$$\frac{d\gamma}{d\theta} / \left\| \frac{d\gamma}{d\theta} \right\|: S^1 \rightarrow S^{k+1}$$

(curve)



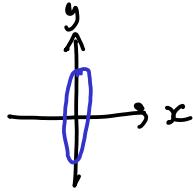
projection along
this axis gives
an immersion

($k=1$)

has image w. complement that is open & dense by Sard's thm.

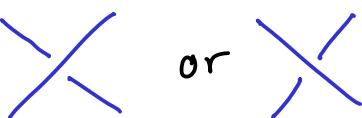
when $k > 0$

Ex For $K = \{0\} \times S^1 \subseteq \mathbb{R}^3$, $\text{pr}(K) = \{0\} \times [-1, 1] \subseteq \mathbb{R}^2$, but a small generic rotation gives



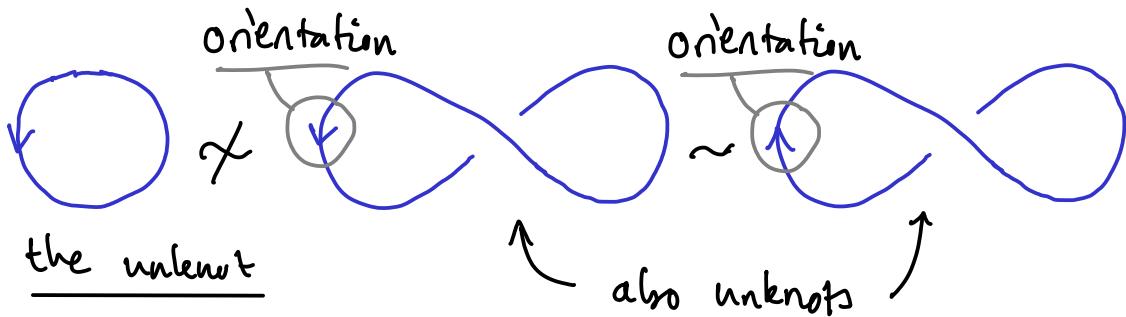
A knot diagram is an immersed curve in \mathbb{R}^2 with

- only transverse double points, called crossings, and
- additional data: which branch is above / below at each crossing

e.g.: 

and smooth iso. class of a link.
(with $\text{pr} = \text{diagram}$)

For the study of parametrised knots, we also equip each component with an orientation.



Two knot diagrams are isotopic (\sim) if they differ by an ambient isotopy of \mathbb{R}^2 .

Isotopic knot diagrams clearly give rise to isotopic links in \mathbb{R}^3 .

The question whether two diagrams in \mathbb{R}^2 are isotopic can be reduced to combinatorics. E.g. use polygonal approximations, Riemann mapping then, isotopy extension then....

Exercise 18.) Classify all link diagrams without crossings. up to isotopy of diagrams.

Exercise 19.) Show that there is a bijective corr. between connected knot diagrams/iso. & embedded conn. graphs $\subseteq \mathbb{R}^2$ w. edges coloured by $+, -$ /iso. Which planar directed graphs corr. to knots?

Hint: 

Exercise 20.) Show that there are precisely two diffeomorphisms $\gamma: S^1 \rightarrow S^1$ up to isotopy. In particular, two parametrisations of a knot

$$\gamma_i: S^1 \rightarrow K \subseteq \mathbb{R}^n, \quad i=0,1,$$

which induce the same orientation are always isotopic.



Some knots are not invertible, i.e. there is no isotopy from K to itself that reverses orientation.