

S III Knot theory

In knot theory we study the question of the classification of subsets

$$K \subseteq M^n$$

up to a relation such as

- Diffeomorphism of M , or even stronger:
- Smooth isotopy of M

$$\underline{\Phi} : M \times [0,1] \rightarrow M \quad \text{smooth}$$

$$\underline{\Phi}_t = \underline{\Phi}|_{M \times \{t\}} \quad \text{diffeomorphism } \forall t$$

$$\underline{\Phi}_0 = \text{id}_M$$

infinitesimal generator

Fact • A smooth isotopy is determined by $V_t(p) = \dot{\underline{\Phi}}_t(p) = \frac{d}{dt} \underline{\Phi}_t(p) \in T_{\underline{\Phi}_t(p)} M$

Reason: Unicity of solutions to ODE: $\begin{cases} \dot{\underline{\Phi}}_0(p) = p \\ \dot{\underline{\Phi}}_t(p) = V_t(\underline{\Phi}_t(p)) \end{cases}$

- A diffeomorphism is isotopic to $\text{id}_M \Leftrightarrow$ It lies in the same component $\pi_0(\text{Diff}^\infty(M))$ as id_M , where the topology in $\text{Diff}^\infty(M)$ is the ∞ -dim. Fréchet Lie group with topology in which convergence = uniform C^k -convergence for all $k > 0$ (For simplicity: M compact)

- $\underline{\Phi}_t \in \text{Diff}^\infty(M)$ is a smooth path, $\frac{d}{dt} \underline{\Phi}_t = V_t \in T_{\underline{\Phi}_t} \text{Diff}^\infty(M)$

$\pi_0(\text{Diff}^\infty(S^1))$ is not known

Also $\pi_0(\{g \in \text{Diff}^\infty(\mathbb{R}^n) \mid g|_{\mathbb{R}^n \setminus B^1} = \text{id}_{\mathbb{R}^n}\})$ is unknown.

$$\underline{\text{Thm}} \quad \pi_0(\text{Diff}^\infty(S^n)) = \{[\text{id}], [\text{reflection}]\}$$

n = 2 (Smale '68)
n = 3 (Cerf '64)

Not true for n=6, ... $|\pi_0(\text{Diff}^\infty(S^6))| = 2 \cdot 28$ (Milnor, Cerf, Smale)

Typically we are interested in the case when $K \subseteq M^n$ is a submanifold, by which we mean

Def $K \subseteq M$ is a submanifold if each $p \in K$ has a nbhd $U \stackrel{\text{open}}{\subseteq} M$ that admits a local chart $\gamma: U \rightarrow \mathbb{R}^n$ in which $\gamma(K) = \mathbb{R}^k \times \{0\} \subseteq \mathbb{R}^n$

Implicit function thm: K is a submanifold $\Leftrightarrow K$ is locally of the form $K \cap U = f^{-1}(0)$, where $f: U \xrightarrow{C^\infty} \mathbb{R}^{n-k}$ ($n-k$ = codimension of K)
0 regular value

Rmk • A submanifold of \mathbb{R}^N is the same as a manifold
• Any submanifold is a manifold, and the inclusion map is a smooth injective immersion, i.e. the differential is everywhere injective

$(T_p\gamma: T_pK \rightarrow T_{\gamma(p)}M \text{ injective for all } p)$

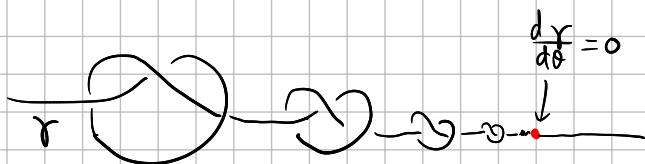
Conversely, a useful way to see that a subset is a submanifold is to verify that it is the image under such a map;

Thm If $\gamma: K \hookrightarrow M$ is a proper (e.g. K compact) smooth injective immersion, then $\gamma(K) \subseteq M$ is a submanifold.

$(T_p\gamma: T_pK \rightarrow T_{\gamma(p)}M \text{ injective for all } p)$

Here, we study one-dimensional closed knots $K^1 \subseteq S^3$, i.e admitting a smooth parametrisation

$$\gamma: S^1 \sqcup \dots \sqcup S^1 \xrightarrow{C^\infty} S^3 \quad d\gamma/d\theta \neq 0 \text{ everywhere}$$



A mild knot (not submanifold)

The existence of a smooth isotopy follows from a similar condition: a smooth family of parametrized submanifolds can be generated by an ambient smooth isotopy.

Thm (Isotopy extension thm) If $\gamma: K \times [0,1] \xrightarrow{C^\infty} M$ smoothly parametrised a family of submanifolds, more precisely: γ_t proper, injective, immersion,
then there exists a smooth isotopy $\Phi_t: M \rightarrow M$ s.t. $\gamma_t = \Phi_t \circ \gamma_0$.
also called isotopy of submanifolds



↙ $\frac{d}{dt} \gamma_t = 0$ or γ not smooth as a map from $K \times [0,1]$

Here the isotopy extension theorem does not apply
(this is not an isotopy of knots)

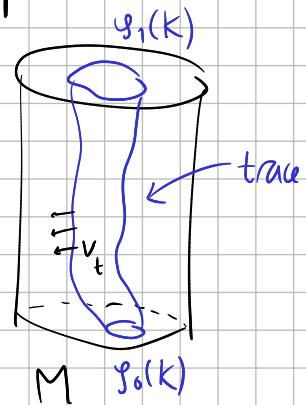
Idea of proof Key point: Above thm implies that

$$K \times [0,1] \hookrightarrow M \times [0,1]$$

$$(p, t) \mapsto (\varphi_t(p), t)$$

$$[0,1]$$

parametrizes a submanifold: the trace of the family of submanifolds



$$v_t(p) := \dot{\varphi}_t(p) \in T_{\varphi_t(p)} M \text{ smooth vector field}, \quad (v_t(p), 0) \in T_{(\varphi_t(p), 0)} (M \times [0,1])$$

smooth vector field defined along the trace

Goal: Construct a smooth extension of v_t to a globally defined vector field V_t , $V_t|_{g_t(K)} = v_t$

- Local extensions exist by "definition of smoothness".

$\Rightarrow \exists$ smooth local extensions to ambient mfd.

- Use bump functions/tubular neighbourhood to patch together extensions & make support confined to small nbhd of $g_t(K)$

□

Knot diagrams & Reidemeister moves

The isotopy question in S^3 is equivalent to that in \mathbb{R}^3 :

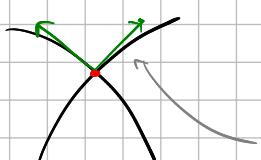
Obviously: Any $\text{codim} \geq 1$ knot $K \subseteq S^n$ can be perturbed (say by $A \in SO(4)$) so that it ends up inside $\mathbb{R}^n = S^n - \{N\}$

Exercise 37 Use Sard's thm to show that two $\text{codim} \geq 2$ submanifolds in $\mathbb{R}^n = S^n - \{N\}$ are isotopic in $S^n \Leftrightarrow$ they are isotopic in \mathbb{R}^n .

Thm For any smoothly parametrised knot $\gamma: K^1 \hookrightarrow \mathbb{R}^3$, for an "generic" open & dense choice of $A \in SO(3)$, the image under the orthogonal projection $\text{pr}: \mathbb{R}_{xyz}^3 \rightarrow \mathbb{R}_{xy}^2$ satisfies the following:

$\text{pr} \circ A \circ \gamma$ is an

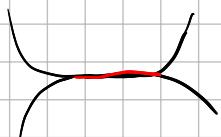
- immersed closed curve, with



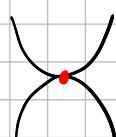
- only transverse double points

velocity vectors span a 2-dim plane

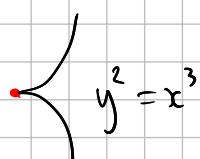
Ex For a generic rotation, we will thus not see a projection with:



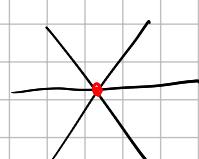
non-discrete
intersection



self-tangency



cusp



triple point.

Idea of proof.

$\frac{dx}{d\theta} / \left\| \frac{dx}{d\theta} \right\| : K \rightarrow S^2$ is smooth since $\frac{dy}{d\theta} \neq 0$

Sard's thm: regular values (= complement of image) are open and dense. The complement of this image is precisely the directions along which the projection is immersed.

For double points

one must analyze

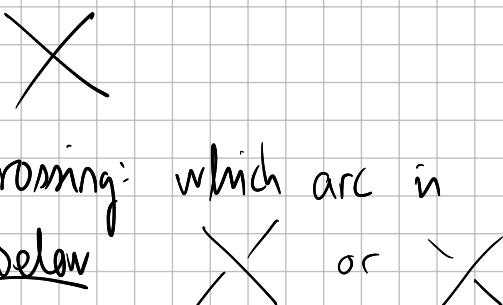
$$r \times r : K \times K \setminus \{(0,0)\} \xrightarrow{\quad \text{"diagonal"} \quad} S^2 \\ (\theta_1, \theta_2) \mapsto r(\theta_1) - r(\theta_2) / \|r(\theta_1) - r(\theta_2)\| \quad \square$$

Ex The unknot: $\{0\} \times S^1 \subseteq \mathbb{R}^3$



Knot diagram: A closed immersed curve in \mathbb{R}^2 with

- transverse double point
- additional data at each crossing: which arc is on top and which is below



Obviously: A smooth isotopy class of knot diagrams induces a

well-defined isotopy class of knots (z -coordinate can be recovered up to smooth isotopy of knot).