

Szemerédi's regularity lemma and graph limits

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In honour of

Endre Szemerédi.

Partly based on papers by Szemerédi, Lovász, Szegedy, Borgs, Chayes, Sós, Vesztergombi, Simonovits, Diaconis, Janson and others.

Szemerédi's regularity lemma

Let G be a graph, with vertex set V . If X and Y are subsets of V , let $e_G(X, Y)$ be the number of edges between X and Y . If U and W are disjoint subsets of V and $\varepsilon > 0$, we say that (U, W) is ε -regular if there exists $d \in [0, 1]$ such that

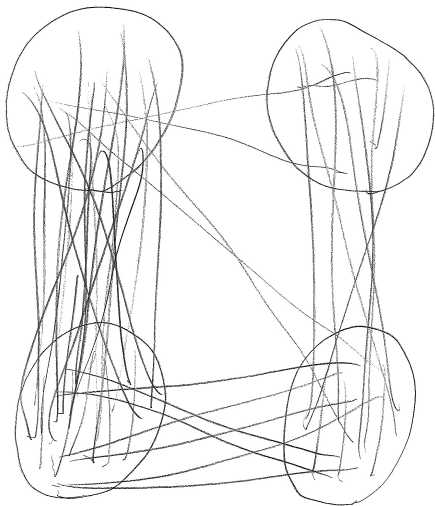
$$\left| \frac{e_G(X, Y)}{|X| \cdot |Y|} - d \right| \leq \varepsilon$$

for all $X \subseteq U$ and $Y \subseteq W$ such that $|X| \geq \varepsilon|U|$ and $|Y| \geq \varepsilon|W|$. Finally, a partition V_1, \dots, V_k of V is a equipartition if $||V_i| - |V_j|| \leq 1$ for all i, j .

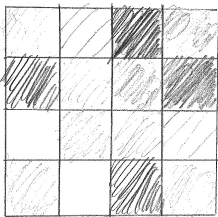
Theorem (Szemerédi's regularity lemma - one version)

Given m and $\varepsilon > 0$, there exists $M = M(m, \varepsilon)$ such that if G is any graph with at least M vertices, then for some ℓ with $m \leq \ell \leq M$, G has an equipartition into ℓ sets V_1, \dots, V_ℓ , such that all but $\varepsilon \ell^2$ pairs (V_i, V_j) are ε -regular.

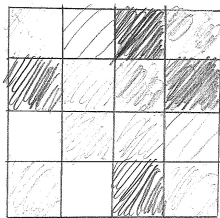
Thus, any graph can be partitioned like this:



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0.4	0.2	1	
0.6	0.3		1
0		0.3	0.2
	0	0.6	0.4

From graphs to functions

Thus large graphs can be approximated by piecewise constant functions on $[0, 1]^2$

This suggests that symmetric functions $[0, 1]^2 \rightarrow [0, 1]$ (“graphons”) can be seen as limits of large graphs, and conversely.

Definition (in principle)

A sequence G_1, G_2, \dots of graphs with $|G_n| \rightarrow \infty$ converges to a graphon $W : [0, 1]^2 \rightarrow [0, 1]$ if there is a sequence of Szemerédi partitions of G_n such that the corresponding densities, regarded as functions on $[0, 1]^2$ converge to W .

Subgraph densities

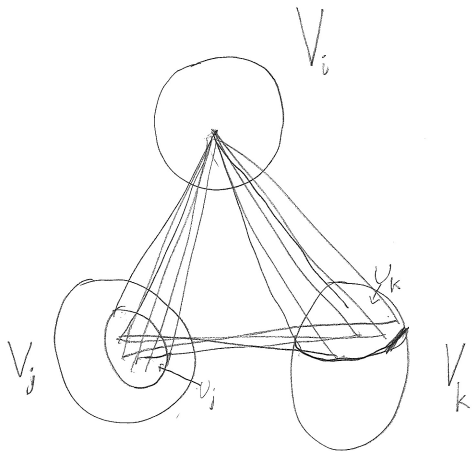
Let G be a graph with a Szemerédi partition V_1, \dots, V_ℓ , and edge densities d_{ij} . Let $|G| = n$; thus each $|V_i| \approx n/\ell$.

Fix i and j and assume that (V_i, V_j) is ε -regular. Then most (all but $O(\varepsilon|V_i|)$) of the vertices in V_i have at least $(d_{ij} - \varepsilon)|V_j|$ neighbours in V_j .

(Otherwise there would be a large bad set $B \subset V_i$ with $e(B, V_j) < (d_{ij} - \varepsilon)|B||V_j|$, violating the definition of ε -regularity.)

Similarly, most vertices in V_i have at most $(d_{ij} + \varepsilon)|V_j|$ neighbours in V_j .

Triangles



Assume that (V_i, V_j) , (V_i, V_k) , (V_j, V_k) are ε -regular. Then most vertices in V_i have $(d_{ij} \pm \varepsilon)|V_j|$ neighbours in V_j and $(d_{ik} \pm \varepsilon)|V_k|$ neighbours in V_k ; moreover, denoting these sets of neighbours by U_j and U_k , the number of edges between them is

$$e(U_j, U_k) = (d_{jk} \pm \varepsilon)|U_j||U_k| = (d_{ij}d_{ik}d_{jk} + O(\varepsilon))(n/\ell)^2.$$

This holds for most vertices in V_i , and summing over all vertices we find that the number of triangles with one vertex in each of V_i, V_j, V_k is

$$(d_{ij}d_{ik}d_{jk} + O(\varepsilon))(n/\ell)^3.$$

Summing over all i, j, k , including irregular pairs and cases with repetitions, we see that the number of triangles in G is

$$n^3 \left(\ell^{-3} \sum_{i,j,k=1}^{\ell} d_{ij} d_{ik} d_{jk} + O(\varepsilon) + O(\ell^{-1}) \right)$$

Taking the limit as $\ell \rightarrow \infty$ and $\varepsilon \rightarrow 0$, assuming that d_{ij} correspond to step functions converging to W , we find that the number of triangles is

$$n^3 \iiint W(x, y) W(x, z) W(y, z) dx dy dz + o(n^3).$$

General subgraph counts

The arguments extend to counts of other subgraphs.

Definition

If F is any fixed graph, with $|F| = f$, let $t(F, G)$ denote the number of (labelled) copies of F in G , divided by $|G|^f$.

Definition

A sequence of graphs G_n with $|G_n| \rightarrow \infty$ converges to a graphon W if

$$t(F, G_n) \rightarrow t(F, W) := \int_{[0,1]^f} \prod_{ij \in E(F)} W(x_i, x_j) dx_1 \cdots dx_f.$$

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Definition (in principle)

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Definition (with graph limits)

A sequence G_1, G_2, \dots of graphs with $|G_n| \rightarrow \infty$ is p -quasirandom if $G_n \rightarrow p$ (the constant graphon $W(x, y) = p$).

Random graphs from Szemerédi partitions

To construct a graph with a given Szemerédi partition V_1, \dots, V_ℓ and given densities d_{ij} :

Take ℓ sets of vertices V_1, \dots, V_ℓ of equal size. For each pair (V_i, V_j) , add edges between them at random, with probability d_{ij} for each edge. (Independently. Toss a (biased) coin for each pair of vertices in $V_i \times V_j$ to decide whether to add an edge.)

Random graphs from graphons

Let $W : [0, 1]^2 \rightarrow [0, 1]$ be a graphon. Let $n \geq 1$. Construct a random graph G_n with vertex set $\{1, \dots, n\}$ as follows:

Construction 1.

Let $x_i = i/n$.

For each pair (i, j) with $i < j$, add an edge ij with probability $W(x_i, x_j)$.

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Theorem

$G_n \rightarrow W$ almost surely.

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Theorem

Graph limits may be described by distributions of infinite random graphs H_∞ .

Graphons from random graphs

Let H_∞ be the infinite random graph constructed above. Let

$$I_{ij} = \begin{cases} 1, & \text{there is an edge } ij \\ 0, & \text{there is no edge } ij. \end{cases}$$

Then I_{ij} is an *exchangeable* array of indicator random variables.
(The distribution is invariant under permutations.)

General representation theorem for exchangeable arrays by Aldous and Hoover \implies

$$I_{ij} = f(x_i, x_j, \xi_{ij}), \quad i < j,$$

for some function f and x_i, ξ_{ij} i.i.d. uniform in $[0, 1]$.

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Theorem

$$G_n \rightarrow W.$$

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In other cases they appear as alternatives:

a proof may be given either by the regularity lemma (involving combinatorial arguments, and $\varepsilon \rightarrow 0$)

or by graph limits (involving graphons and analytic arguments).

In any case, they both tell us that there is order in chaos.

Congratulations to the Abel Prize!