

A rigorous lower bound for the stability regions of the quadratic map

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Abstract

We establish a lower bound on the measure of the set of stable parameters a for the quadratic map $Q_a(x) = ax(1 - x)$. For these parameters, we prove that Q_a either has a single stable periodic orbit or a period-doubling bifurcation. From this result, we also obtain a non-trivial upper bound on the set of stochastic parameters for Q_a .

Keywords: Quadratic map, periodic orbit, period doubling bifurcation, interval analysis.

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1 Introduction

The quadratic map (often referred to as the *logistic map*)

$$Q_a : [0, 1] \rightarrow [0, 1] \quad x \mapsto ax(1 - x), \tag{1}$$

is arguably the most studied discrete dynamical system. Beginning with the famous article by Robert May [Ma76], the intricate properties of this dynamical system have gradually been revealed, see e.g. [CE80], [Ep85], [Fe79], [La82], [Ly02]. The latter article succinctly states that almost every parameter $a \in [0, 4]$ is either *regular* or *stochastic*. To be more precise, a parameter is called *regular* if Q_a has an attracting cycle. In this case the cycle is unique, and attracts almost all orbits in $[0, 1]$. A parameter is called *stochastic* if Q_a has an absolutely continuous invariant measure. In this case, the measure is unique, and almost all orbits in $[0, 1]$ are asymptotically equidistributed with respect to it.

For convenience, let us denote the set of regular parameters by \mathcal{R} , and the stochastic parameters by \mathcal{S} . The result by Lyubich then states that $|\mathcal{R}| + |\mathcal{S}| = 4$, where $|\cdot|$ denotes Lebesgue measure.

Today, it is well-known that \mathcal{S} has positive measure, see e.g. [BC85], [BC91], [Ja81]. Remarkably, until very recently (see [LT06]), there has been no non-trivial estimates on the measure of \mathcal{S} . And, as the authors of [LT06] point out, the result¹ $|\mathcal{S} \cap I^*| > 0.97|I^*| > 10^{-5000}$ with $I^* = [2 - 10^{4990}, 2]$ is not a good estimate of $|\mathcal{S}|$. Seeing that \mathcal{R} is an open (and dense [Sw92]) set, it trivially follows that it has positive measure. The aim of this work is to try to obtain a good *lower* bound on the measure of \mathcal{R} . In light of [Ly02], this automatically translates to a good *upper* bound on the measure of \mathcal{S} .

Theorem 1 (Main Theorem) *The set of regular parameters for the quadratic map satisfies the lower bound: $|\mathcal{R} \cap [2, 4]| \geq 1.61394824439594656781$.*

We believe that this lower bound is quite close to the true measure. According to non-rigorous numerical experiments ([Si08]) the measure of the regular set, beyond the first period doubling cascade (at $r^* \approx 3.569945672$) is estimated to be $|\mathcal{R} \cap [r^*, 4]| \approx 0.0455857$, i.e., \mathcal{R} constitutes roughly 10.6% of the set $[r^*, 4]$. Our bound captures more than 10.2% of these parameters, which means that our rigorous result is just slightly less than the non-rigorous estimate. Of course, the non-rigorous estimate may be a gross underestimation of the actual measure, but we find this quite unlikely.

The way we obtain our main result is by adaptively partitioning the parameter space $\mathbb{A} = [2, 4]$ into subintervals. For each such subinterval \mathbb{A}_i , we attempt to prove that Q_a has a unique, stable periodic orbit, which persists for all $a \in \mathbb{A}_i$. This can be achieved by employing various set-valued versions of fixed point theorems, implemented rigorously using interval analysis.

We also prove the existence of period doubling bifurcations, using a method presented in [WZ09]. Note that, although the set of parameters at which a period doubling occurs has measure zero, this step is not entirely superficial. It allows us to join the two parameter sets that correspond to stable periodic orbits before and after a period doubling. This produces larger connected parameter sets within each period doubling cascade, and thus adds measure to our final bound.

2 Three methods for verifying the existence of a stable orbit

Our algorithm for computing a lower bound for the measure of \mathcal{R} uses the following three methods for verifying the existence of a stable orbit:

- the Brouwer theorem,
- the method of backward shooting,
- the modified interval Krawczyk operator.

¹This results concerns the quadratic map $f_b(x) = x^2 - b$. Thus the parameter $b = 2$ corresponds to our parameter $a = 4$.

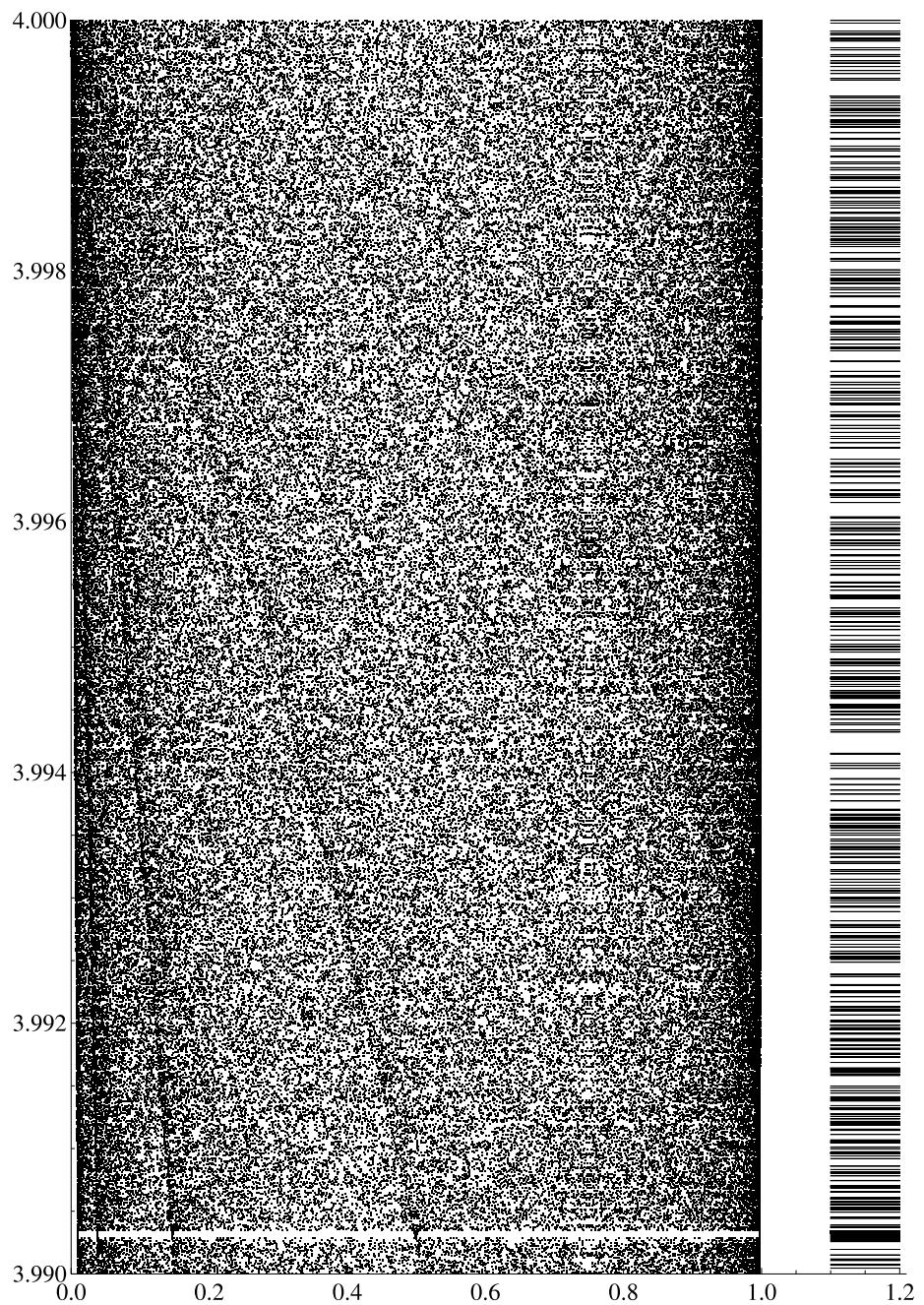


Figure 1: The bifurcation diagram for the quadratic map for parameters $a \in [3.99, 4]$. To the right of the main bifurcation diagram, verified stable windows have been marked as black rectangles.

The three methods are increasing in computational complexity, and therefore, when proving the existence of a stable orbit, we first use the Brouwer theorem. If this method fails, we apply the method of backward shooting. If we still have no success, we switch to the modified interval Krawczyk method, provided the assumptions of this method are satisfied.

2.1 The method based on the Brouwer theorem

This is the simplest method, and it relies upon the fact that our goal is to prove the existence of a stable periodic orbit. Let \mathbb{A} be a closed interval of parameters for which we expect the existence of a stable periodic orbit for Q_a . Let x_1 be an approximate p -periodic point for the parameter $a = \text{mid}(\mathbb{A})$ and let X_1 be a closed interval containing x_1 in its interior. Using interval arithmetic we compute the sequence X_i , $i = 2, \dots, p$ such that for all $a \in \mathbb{A}$

$$Q_a(X_i) \subset X_{i+1}, \quad i = 1, \dots, p-1$$

Since the orbit is expected to be attracting, it might happen that $X_p \subset X_1$. In that case the Brouwer theorem guarantees that for each $a \in \mathbb{A}$ there exists a fixed point $x_1^a \in X_1$ for the map Q_a^p . It remains for us to verify that $\{x_i^a\}_{i=1}^p$ is the p -periodic stable orbit for Q_a .

The verification that p is the principal period of x_1^a can be simply done by checking if the computed enclosure of the trajectory satisfies the condition

$$X_1 \cap X_i = \emptyset, \quad \text{for } i = 2, \dots, p \text{ such that } i-1 \text{ divides } p \quad (2)$$

In order to verify the stability of the trajectory of x_1^a it is enough to check if

$$|Q'_{\mathbb{A}}(X_1) \cdot Q'_{\mathbb{A}}(X_2) \cdots Q'_{\mathbb{A}}(X_p)| < 1 \quad (3)$$

Summarizing, we had prove the following

Lemma 2 *Assume that Algorithm 1 is called with the arguments \mathbb{A} and X_1 . If the algorithm stops and returns true then for each $a \in \mathbb{A}$ the computed enclosure (X_1, \dots, X_p) contains the unique p -periodic stable orbit for Q_a .*

The above method is very fast, but has some disadvantages compared to the methods described in the following sections. First, given that we always examine an interval of parameters \mathbb{A} rather than a single parameter, the condition $Q_{\mathbb{A}}(X_p) \subset X_1$ might fail.

Second, the initial interval X_1 cannot be too small since we intend to verify the existence of a stable orbit for an interval \mathbb{A} . As the “convergence” of X_1 to the periodic orbit is linear (like the contraction of the map), it is very weak for parameters close to bifurcation parameters. Therefore the computed enclosure (X_1, \dots, X_p) of the periodic orbit may be quite wide. This fact can result in that the stability criterion (3) is not satisfied.

The methods described in the next sections avoid such disadvantages. The computational complexity, however, is larger.

Algorithm 1: verify stability by means of the Brouwer theorem

Data: \mathbb{A} - interval,
 X_1, \dots, X_p - intervals

```

1 begin
2   for  $i \leftarrow 2$  to  $p$  do
3      $X_i \leftarrow Q_{\mathbb{A}}(X_{i-1})$ ;
4     if  $p \bmod i - 1 = 0$  and  $X_i \cap X_1 \neq \emptyset$  then
5       return false;
6     if  $Q_{\mathbb{A}}(X_p) \not\subset X_1$  then
7       return false;
8      $X_1 \leftarrow Q_{\mathbb{A}}(X_p)$ ;
9     Interval product  $\leftarrow 1$ ;
10    for  $i \leftarrow 1$  to  $p$  do
11      product  $\leftarrow Q'_{\mathbb{A}}(X_i) \times$  product;
12      if not  $|product| < 1$  then
13        return false;
14    return true;
15 end

```

2.2 The method of backward shooting

One of the most efficient methods for verifying the existence of isolated zeros for a map is the interval Newton method (see e.g. [AH83], [Kr86], [KN84]). Given a smooth function $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$, an interval vector² X , and a point $\bar{x} \in X$ we define the interval Newton operator by

$$N(F, \bar{x}, X) = \bar{x} - DF^{-1}(X)F(\bar{x}). \quad (4)$$

Theorem 3 Let X be an interval vector, $\bar{x} \in X$, and $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be smooth. Assume that $DF(X)$ is invertible as an interval matrix. If the interval Newton operator satisfies

$$N(F, \bar{x}, X) \subset X$$

then the map F has a unique zero x^* in the set X . Moreover, $x^* \in N(F, \bar{x}, X)$.

This theorem can be adopted to the special situation of proving the existence of periodic orbits for one-dimensional maps, even for very high periods. In this section we recall the method of backward shooting introduced in [Ga02].

The question of the existence of a periodic point for a map $f : \mathbb{R} \rightarrow \mathbb{R}$ of principal period p can be transformed to finding a zero of the function

$$F(x_1, \dots, x_p) = (x_2 - f(x_1), \dots, x_p - f(x_{p-1}), x_1 - f(x_p)), \quad (5)$$

with the additional assumption that the zero of F has pairwise different coefficients. The following theorem is proved in [Ga02]:

²In the sequel we will call a Cartesian product of closed intervals an *interval vector*.

Theorem 4 Let $X = (X_1, \dots, X_p)$ be an interval vector, $\bar{x} = (\bar{x}_1, \dots, \bar{x}_p) \in X$, and let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a smooth map. Define F as in (5). Let us assume that $A_k, G_k, H_k, k = 1, \dots, p$ are intervals such that

$$\begin{aligned} 0 &\notin A_k, \quad k = 1, \dots, p \\ f'(X_k) &\subset A_k, \quad k = 1, \dots, p \\ f(\bar{x}_k) - \bar{x}_{(k \bmod p)+1} &\in G_k \end{aligned} \tag{6}$$

$$(1 - A_1^{-1} \cdots A_p^{-1}) \sum_{i=1}^p A_1^{-1} \cdots A_i^{-1} G_i \subset H_1 \tag{7}$$

$$A_k^{-1} (H_{(k \bmod p)+1} + G_k) \subset H_k, \quad k = 2, \dots, p \tag{8}$$

Then $DF(X)^{-1}F(\bar{x}) \subset H = (H_1, \dots, H_p)$, and $N(F, \bar{x}, X) \subset \bar{x} - H$.

The above theorem gives a precise algorithm for proving the existence of periodic points for a map $f : \mathbb{R} \rightarrow \mathbb{R}$. If $\bar{x} = (\bar{x}_1, \dots, \bar{x}_p)$ is a good candidate for a periodic orbit, we can choose X to be a small interval vector centered at \bar{x} . Then, G_k and H_k can be computed directly by means of the formulas (6–8), provided that none of the A_k contain zero. If $N(F, \bar{x}, X) \subset X$, then by theorem (3) F has a (unique) zero in the set $N(F, \bar{x}, X)$, which corresponds to a periodic point of period p . As a final step, we must also verify that p is the minimal period of the found periodic point, and that this orbit is stable. This can be done by verifying conditions (2–3) in the same way as in Algorithm 1.

Remark 5 In our algorithm, which verifies the existence of stable periodic orbits for the map Q_a , we use Theorem 3 applied to the map F defined as in (5) with $f = Q_{\mathbb{A}}$, where \mathbb{A} is an interval of parameters. The interval Newton operator is computed as described in Theorem 4.

The method of backward shooting, although very efficient, cannot be used to prove the existence of a superstable periodic orbit, or even an orbit which is very close to a superstable orbit. In this type of situation, we use a special version of the interval Krawczyk operator.

2.3 The interval Krawczyk method for superstable orbits

A superstable orbit appears when the critical point of Q_a is a periodic point. Let (x_1, x_2, \dots, x_p) be a periodic orbit, and assume that x_1 is the critical point. It is easy to see that, in this situation, we cannot apply the backward shooting method, since $Q'_a(x_1) = 0$. Note, however, that the derivative of $F(x_1, \dots, x_p) = (x_2 - Q_a(x_1), \dots, x_p - Q_a(x_{p-1}), x_1 - Q_a(x_p))$ has the following form:

$$DF(x_1, \dots, x_p) = \begin{bmatrix} -Q'_a(x_1) & 1 & 0 & \cdots & 0 \\ 0 & -Q'_a(x_2) & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & -Q'_a(x_{p-1}) & 1 \\ 1 & 0 & \cdots & 0 & -Q'_a(x_p) \end{bmatrix}.$$

Since we are assuming that x_1 is a critical point, we have $Q'_a(x_1) = 0$. This means that the solution of the linear equation $DF(x_1, \dots, x_p) \cdot y = z$, where $y = (y_1, \dots, y_p)$, $z = (z, \dots, z_p)$ is given by

$$\begin{cases} y_2 &= z_1 \\ y_3 &= z_2 + Q'_a(x_2)y_2 \\ y_4 &= z_3 + Q'_a(x_3)y_3 \\ \dots & \\ y_p &= z_{p-1} + Q'_a(x_{p-1})y_{p-1} \\ y_1 &= z_p + Q'_a(x_p)y_p \end{cases} \quad (9)$$

Despite this, we cannot use this approach for superstable orbits when solving the linear equation by means of the interval Newton operator. This is because the coefficient $Q'_a(X_1)$ is then not equal to zero - it is an interval *containing* zero. Of course, one might consider using Gaussian elimination for solving the linear system which appears in the interval Newton operator. In this special case, however, the computational complexity can be significantly reduced by using the interval Krawczyk operator instead.

The interval Krawczyk operator is defined by

$$K(F, \bar{x}, X, C) = \bar{x} - C \cdot F(\bar{x}) + (\text{Id} - C \cdot DF(X))(X - \bar{x}) \quad (10)$$

Theorem 6 *Let C be an isomorphism, and let $\bar{x} \in X$, where X is an interval vector. If the interval Krawczyk operator (10) satisfies*

$$K(F, \bar{x}, X, C) \subset \text{int } X$$

then the map F has a unique zero in $x^ \in X$. Moreover, $x^* \in K(F, \bar{x}, X, C)$.*

Observe that the method only requires that C be an (arbitrary) isomorphism. For the method to work well, however, C should be chosen to be an approximate inverse of $DF(\bar{x})$. The main idea of our approach for proving the existence of superstable periodic orbits (and also nearly superstable ones) is to choose the matrix J as an approximation of $DF(\bar{x})$, and then force the coefficient $J_{11} = 0$. Given this, we choose C to be the inverse of J , which always exists. Furthermore, it can be computed relatively fast – the computational complexity is quadratic with respect to the period p , as we will see below.

Another advantage, in comparison to Gaussian elimination, is that this approach is more memory efficient. In fact, we need not store neither C nor $\text{Id} - C \cdot DF(X)$, which significantly decreases memory usage, especially for large periods – see Algorithm 2. The only storage we need to cater for are the values of $C \cdot F(\bar{x})$ and $(\text{Id} - C \cdot DF(X))(X - \bar{x})$. The value of $C \cdot F(\bar{x})$ can be computed by means of (9). What remains for us to show is the algorithm for the computation of $(\text{Id} - C \cdot DF(X))(X - \bar{x})$.

Lemma 7 *Assume that Algorithm 2 is called with its arguments, and assume that $a_1 = 0$. Then the algorithm always stops and returns an interval vector r*

Algorithm 2: solve linear system

Data: a_1, \dots, a_p - scalars,
 A_1, \dots, A_p - intervals,
 $\bar{x} = (\bar{x}_1, \dots, \bar{x}_p)$ - a vector,
 $X = (X_1, \dots, X_p)$ - an interval vector

```

1 begin
2    $r = (r_1, \dots, r_p)$  : an interval vector;
    $r \leftarrow 0$ ;
   for  $i \leftarrow 1$  to  $p$  do
3     Interval product  $\leftarrow A_i - a_i$ ;
      $r_{(i \bmod p)+1} \leftarrow (r_{(i \bmod p)+1} + \text{product} \times (X_i - \bar{x}_i))$ ;
     for  $j \leftarrow i+1$  to  $p$  do
4       product  $\leftarrow$  product  $\times a_j$ ;
        $r_{(j \bmod p)+1} \leftarrow (r_{(j \bmod p)+1} + \text{product} \times (X_j - \bar{x}_j))$ ;
5   return  $r$ ;
6 end
```

which is an upper bound for the interval vector $(Id - C \cdot D)(X - \bar{x})$, where

$$D = \begin{bmatrix} -A_1 & 1 & 0 & \dots & 0 \\ 0 & -A_2 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & -A_{p-1} & 1 \\ 1 & 0 & \dots & 0 & -A_p \end{bmatrix}, C = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & -a_2 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & -a_{p-1} & 1 \\ 1 & 0 & \dots & 0 & -a_p \end{bmatrix}^{-1}$$

Proof: It is easy to see that the matrix $M := Id - C \cdot D$ has the form

$$\begin{bmatrix} a_p \dots a_2 A_1 & a_p \dots a_3 (A_2 - a_2) & \dots & a_p (A_{p-1} - a_{p-1}) & A_p - a_p \\ A_1 & 0 & \dots & 0 & 0 \\ a_2 A_1 & A_2 - a_2 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{p-2} \dots a_2 A_1 & a_{p-2} \dots a_3 (A_2 - a_2) & \dots & 0 & 0 \\ a_{p-1} \dots a_2 A_1 & a_{p-1} \dots a_3 (A_2 - a_2) & \dots & A_{p-1} - a_{p-1} & 0 \end{bmatrix} \quad (11)$$

The above form can be obtained by the application of (9) to the columns of D . Hence, the coefficients of the matrix M are given by

$$M_{(j \bmod p)+1,i} = \begin{cases} 0 & \text{for } j = 1, \dots, i-1 \\ A_i - a_i & \text{for } j = i \\ a_j M_{j-1,i} & \text{for } j = i+1, \dots, p \end{cases} \quad (12)$$

Define $r = (Id - C \cdot DF(X))(X - \bar{x})$. Then

$$r = \sum_{i=1}^p M_{\cdot,i} (X_i - \bar{x}_i), \quad (13)$$

where $M_{\cdot,i}$ denotes the i -th column of the matrix M . The above sum corresponds to the external loop in the algorithm indexed also by i . In the internal loop of the algorithm (indexed by j), the variable 'product' contains precisely the coefficients of the i -th column of the matrix M , as given by the recursive formula (12).

Since all operations used in the algorithm are always well defined in interval arithmetic (extended to NaN cases), the algorithm always returns a valid upper bound for $(\text{Id} - C \cdot D)(X - \bar{x})$. \blacksquare

The above lemma gives us a tool for computing the interval Krawczyk operator for a periodic orbit which is (or is close to) superstable. To be more precise: the interval Krawczyk operator is used to prove the *existence* of such a periodic orbit. In addition to this, we need to check if this orbit has principal period p , and if it is stable. As in the method of backward shooting one needs to verify the conditions (2–3).

3 A method for verifying the existence of period doublings for 1D maps

The methods described in the earlier sections allow us to prove the existence of stable periodic orbits for parameter ranges well separated from bifurcations. Our aim, however, is to give as good as possible lower bound for the measure of parameters for which stable periodic orbit exists. Therefore, it is important to take into account neighborhoods of parameters for which period doublings occur.

A period doubling occurs when the derivative of a stable periodic orbit decreases through the value -1 . When crossing -1 , a new stable periodic orbit arises, with a derivative slightly less than 1 . The existence of the period doubling can be deduced just from higher derivative information of the map at the bifurcation point. This does not, however, give us any information about the size of the set, or the parameter range, on which we have such dynamics.

In the paper [WZ09], a method for proving the existence of period doubling for higher dimensional maps is proposed. In this method, some computable inequalities for the derivatives allow one to deduce the dynamics of a map in an explicitly given neighborhood of the bifurcation point – both in the phase space and in the parameter space.

Here we recall the main definitions and theorems, adopted to the one-dimensional case. Given a map $f : X \rightarrow Y$, we let $\text{dom}(f)$ denote the domain of f . For a map $F : X \rightarrow X$, we will denote its (restricted) set of fixed points by $\text{Fix}(F, U) = \{x \in U \mid F(x) = x\}$.

Definition 1 Let $f : \mathbb{R} \supset \text{dom}(f) \rightarrow \mathbb{R}$ be C^1 . Let $z_0 \in \text{dom}(f)$. We say that z_0 is a hyperbolic fixed point for f iff $f(z_0) = z_0$ and $|f'(z_0)| \neq 1$.

Definition 2 A subset $I \subset \mathbb{Z}$ is called an interval in \mathbb{Z} if there exists an closed interval $[a, b]$, where $a, b \in \mathbb{R} \cup \{\pm\infty\}$ such that $\mathbb{Z} \cap [a, b] = I$.

Definition 3 Consider a map $f : \mathbb{R} \supset \text{dom}(f) \rightarrow \mathbb{R}$. Let $x \in \mathbb{R}$. Any sequence $\{x_k\}_{k \in I}$, where I is an interval in \mathbb{Z} containing zero such that

$$x_0 = x, \quad f(x_i) = x_{i+1}, \quad \text{for } i, i+1 \in I$$

will be called an orbit through x . If $I = \mathbb{Z}_- \cup \{0\}$, then we will say that $\{x_k\}_{k \in I}$ is a full backward orbit through x .

Definition 4 Consider a continuous map $f : \mathbb{R} \supset \text{dom}(f) \rightarrow \mathbb{R}$.

Let $Z \subset \mathbb{R}^n$, $x_0 \in Z$, $Z \subset \text{dom}(f)$. We define

$$\begin{aligned} W_Z^s(z_0, f) &= \{z \mid \forall n \geq 0, f^n(z) \in Z, \lim_{n \rightarrow \infty} f^n(z) = z_0\} \\ W_Z^u(z_0, f) &= \{z \mid \exists \{x_n\} \subset Z \text{ a full backward orbit through } z, \text{ such that} \\ &\quad \lim_{n \rightarrow -\infty} x_n = z_0\} \\ W^s(z_0, f) &= \{z \mid \lim_{n \rightarrow \infty} f^n(z) = z_0\} \\ W^u(z_0, f) &= \{z \mid \exists \{x_n\} \text{ a full backward orbit through } z, \text{ such that} \\ &\quad \lim_{n \rightarrow -\infty} x_n = z_0\} \\ \text{Inv}^+(Z, f) &= \{z \mid \forall n \geq 0, f^n(z) \in Z\} \\ \text{Inv}^-(Z, f) &= \{z \mid \exists \{x_n\} \subset Z \text{ a full backward orbit through } z\} \\ \text{Inv}(Z, f) &= \text{Inv}^+(Z, f) \cap \text{Inv}^-(Z, f) \end{aligned}$$

If f is known from the context, then we will usually drop it and use $W^s(z_0)$, $W_Z^s(z_0)$ etc instead.

Definition 5 [WZ09, Def. 4] Let $f_a : \mathbb{R} \rightarrow \mathbb{R}$, where a belongs to some interval. We say that f_a has a period doubling bifurcation at (a_0, x_0) iff there exists $Z = [a_1, a_2] \times X \subset \mathbb{R} \times \mathbb{R}$, such that the following conditions are satisfied:

- $(a_0, x_0) \in \text{int } Z$, $f_{a_0}(x_0) = x_0$
- there exists a continuous function $x_{fp} : [a_1, a_2] \rightarrow \text{int } X$, such that

$$\text{Fix}(f_a, X) = \{x_{fp}(a)\}$$

- there exist two continuous curves $x_i : [a_0, a_2] \rightarrow \text{int } X$, $i = 1, 2$, such that for $a \in [a_0, a_2]$, the following holds:

$$\begin{aligned} x_1(a_0) &= x_2(a_0) = x_{fp}(a_0) \\ x_1(a) &\neq x_2(a), \quad a \neq a_0 \\ f_a(x_1(a)) &= x_2(a), \quad f_a(x_2(a)) = x_1(a) \\ \text{Fix}(f_a^2, X) &= \{x_1(a), x_2(a), x_{fp}(a)\} \end{aligned}$$

- the dynamics:

for $a \leq a_0$

$$Inv(X, f_a) = \{x_{fp}(a)\}$$

and $x_{fp}(a)$ is an attracting fixed point for f_a .

For $a > a_0$ the maximal invariant set in X $Inv(X, f_a)$ is equal to

$$\overline{W_X^u}(x_{fp}(a), f) \cap (\overline{W_X^s}(x_1(a), f_a^2) \cup \overline{W_X^s}(x_2(a), f_a^2))$$

and it is an interval connecting the points $x_1(a)$, $x_2(a)$.

Note that in the above definition, we assume the existence of a stable periodic orbit for each parameter value $a \in [a_1, a_2]$. Even for a_0 , which has the neutral eigenvalue -1 , the point x_0 is assumed to be attracting.

The following theorem summarizes the numerical method for proving the existence of a period doubling bifurcation for one-dimensional maps.

Theorem 8 [WZ09, Thm.4, Thm.9] Let $Z = [a_1, a_2] \times [x_1, x_2]$ and let $f_a : \mathbb{R} \rightarrow \mathbb{R}$ be a family of maps, such that $[x_1, x_2] \subset \text{dom}(f_a)$ for $a \in [a_1, a_2]$.

A1 Assume there exists a C^k -function ($k \geq 3$), $x_{fp} : [a_1, a_2] \rightarrow (x_1, x_2)$ such that for $a \in [a_1, a_2]$

$$Fix(f_a, [x_1, x_2]) = \{x_{fp}(a)\}$$

A2 Assume that $G : Z \rightarrow \mathbb{R}$, defined as

$$G(a, x) = x - f_a^2(x), \quad \text{for } (a, x) \in Z,$$

is a C^k -function ($k \geq 3$), such that

$$\begin{aligned} \frac{\partial^3 G}{\partial x^3}(Z) &\subset (0, \infty) \\ \frac{\partial^2 G}{\partial x \partial a}(Z) + \frac{\partial^2 G}{\partial x^2}(Z)x'_{fp}([a_1, a_2]) \cdot [0, 1] &\subset (-\infty, 0), \\ \frac{\partial G}{\partial x}(a_1, [x_1, x_2]) &\subset (0, \infty), \\ G(a_2, x_2) > 0, \quad G(a_2, x_1) &< 0, \\ \frac{\partial G}{\partial x}(a_2, x_{fp}(a_2)) &< 0. \end{aligned}$$

A3 Assume that f_a is injective on $[x_1, x_2]$ for each $a \in [a_1, a_2]$, and

$$\begin{aligned} f'_{a_1}(x_{fp}(a_1)) &\in (-1, 1), \\ f'_{a_2}(x_{fp}(a_2)) &< -1, \\ \frac{\partial}{\partial a}(f'_a(x_{fp}(a))) &< 0, \text{ for } a \in [a_1, a_2]. \end{aligned}$$

Then there exists a point $(a_0, x_0) \in Z$ such that f has a period doubling bifurcation at (a_0, x_0) , with the neighborhood from the definition of the period doubling equal to Z .

Let us observe that all assumptions from the above theorem can be verified using rigorous numerics. The existence of the fixed point curve x_{fp} can be established by means of the interval Newton method. Given an enclosure for $x_{fp}(a)$, we can compute its derivative $x'_{fp}(a)$ by differentiating the equation

$$x_{fp}(a) - f_a(x_{fp}(a)) = 0.$$

The other inequalities are easily handled using interval arithmetic, as long as the set Z is a good candidate for the existence of the period doubling bifurcation.

4 The main algorithm

In this section, we will outline the main parts of the algorithm used to bound the measure of stable parameters.

4.1 Finding superstable windows

By a result of Douady and Hubbard ([DH07]), each stable window contains exactly one parameter yielding a superstable periodic orbit. Let $x(a_*)$ denote a new born fixed point for $Q_{a_*}^n$ which is an origin of a stable window. In each case $\frac{\partial}{\partial x} Q_{a_*}^n(x(a_*)) = 1$ and this derivative decreases to -1 along the fixed point curve $x(a)$ when the parameter a increases and results in the next period doubling bifurcation. Hence, for some parameter value a_0 we have $\frac{\partial}{\partial x} Q_{a_0}^n(x(a_0)) = 0$ and the orbit is superstable. This means that the critical point for the quadratic map is on the trajectory of $x(a_0)$.

The above considerations give us a method for detecting superstable orbits. It is enough to solve the equation

$$Q_a^n\left(\frac{1}{2}\right) = \frac{1}{2} \tag{14}$$

with respect to a . Since the above equation is polynomial of the degree 2^n it has finite number of solutions, and any method for detecting zeros of this polynomial may be used. In our application we do not need to estimate all solutions of (14) – in fact a lot of them are complex numbers or even when real, they are out of the range $\mathbb{A} = [2, 4]$. In our algorithm we use the Newton method; the details will be presented in the sequel.

Given a good approximation of a superstable periodic point, say $x(a_0)$, we can also estimate very roughly the size of the entire stable window. This can be done by using the Taylor approximation of the curve $\frac{\partial}{\partial x} Q_a^n(x(a))$, where $x(a)$ is a curve of period- n points. In the first approach, we can use the linear approximation. Put

$$s(a) = \frac{\partial}{\partial a} \left(\frac{\partial}{\partial x} Q_a^n(x(a)) \right)$$

Clearly $s(a_0)$ gives us a linear approximation of how fast the stability of $x(a_0)$ changes. Hence, given that $\frac{\partial}{\partial x} Q_{a_0}^n(x(a_0)) \approx 0$, we can expect that the stable window is roughly

$$d(a_0) = [a_0 + 1/s(a_0), a_0 - 1/s(a_0)] \quad (15)$$

(note that $s(a_0) < 0$) or at least of this magnitude. It is possible to compute a higher order Taylor expansion of this curve (for example by means of automatic differentiation), and then solve for when it is equal to 1 and -1 .

4.2 One iteration of the algorithm.

Assume we have some grid of the parameter domain

$$[2, 4] = \bigcup_{i \in \mathcal{I}} \mathbb{A}_i,$$

where the \mathbb{A}_i are closed intervals (with non-empty interior) such that $\text{int } \mathbb{A}_i \cap \text{int } \mathbb{A}_j = \emptyset$ provided $i \neq j$. To each subinterval \mathbb{A}_i from this grid we attribute one of the following four labels: `unchecked`, `verified`, `periodDoubling`, `small`. The first grid of the interval $\mathbb{A} = [2, 4]$ is created by subdividing the interval \mathbb{A} into 100 equal parts; each subinterval in this primary partition is given the label `unchecked`.

Let $N > 1$ be the maximal period of the stable window we are searching for. This is a parameter of our algorithm, and it remains fixed throughout the computations. One iteration of our algorithm consists of the following steps:

1. Search for superstable orbits
2. Fill parameter gaps
3. Search for parameter domains that contain a stable window, but which are not necessary superstable
4. Fill parameter gaps
5. Scan for period doubling

Note that neither our method of searching for superstable orbits, nor the bisection (step 3 below) produces a uniform partition. Without this non-uniform process, the computational times would become enormous. Below we describe how each one of the above steps are realized.

Searching for superstable orbits. For each subinterval \mathbb{A}_i , we proceed as follows.

- 1.1 If the interval \mathbb{A}_i has a width smaller than 10^{-17} , we label it `small`.
- 1.2 If the interval \mathbb{A}_i is *not* labeled as `unchecked`, we leave it intact, and exit.

- 1.3 Set $a = \text{mid}(\mathbb{A}_i)$. For each $n = 2, \dots, N$ the point a is a seed for the standard Newton method which solves equation (14). In this way we obtain a sequence

$$\mathbb{B}_i = (\mathbb{B}_i^2, \mathbb{B}_i^3, \dots, \mathbb{B}_i^N)$$

such that for $n = 2, \dots, N$ either $\mathbb{B}_i^n = \{a_i^n\}$ if $a_i^n \in \mathbb{A}_i$ is a good candidate for the superstable orbit of the period n , or $\mathbb{B}_i^n = \emptyset$, otherwise.

- 1.4 If $\mathbb{B}_i^n = \emptyset$ for each $n = 2, \dots, N$ then we leave interval \mathbb{A}_i intact, and exit.

- 1.5 For each $\mathbb{B}_i^n = \{a_i^n\}$ we try to prove that such a superstable orbit of principal period n exists on the interval of parameters $\mathbb{A}_i^n = a_i^n + [-10^{-17}, 10^{-17}]$. If we are able to prove stability on the interval \mathbb{A}_i^n then we set $\mathbb{B}_i^n = \{\mathbb{A}_i^n\}$, otherwise $\mathbb{B}_i^n = \emptyset$.

- 1.6 For each $\mathbb{B}_i^n = \{\mathbb{A}_i^n\}$ we proceed as follows. Using the estimation (15) we try to find two numbers $c_i^n, d_i^n \in \mathbb{A}_i$ such that c_i^n is as close as possible to the origin of the window \mathbb{A}_i^n and d_i^n is as close as possible to the end of that window. Next, we try to prove the existence of a stable periodic orbit of period n on the intervals $\mathbb{C}_i^n = c_i^n + [-10^{-17}, 10^{-17}]$ and $\mathbb{D}_i^n = d_i^n + [-10^{-17}, 10^{-17}]$.

- 1.7 We replace \mathbb{A}_i in the current partition by a set of intervals $\mathbb{A}_i^n, \mathbb{C}_i^n, \mathbb{D}_i^n$, on which we were able to verify stability and mark them as **verified**. We also insert the remaining parts of \mathbb{A}_i , and mark them as **unchecked**.

Filling parameter gaps The above method for finding superstable orbits produces a parameter set with many gaps. At this point of the algorithm, we scan our current partition, and try to locate and fill possible gaps in the computed stable windows. The key point is that we do not need to determine a period of a stable window. We assume that if two subintervals \mathbb{A}_i and \mathbb{A}_j with the same period are separated only by intervals marked as **unchecked**, these might form a gap.

Searching for parameter domains that contain a stable window, but which are not necessary superstable This step might seem superfluous at first, but it is very important for proving the existence of period doublings, as well as for extending the primary window of each detected period doubling cascade. Note that the primary window in a cascade has the largest measure in that cascade, so it is very important to extend this window as much as possible.

- 3.1 If the interval \mathbb{A}_i has a width smaller than 10^{-17} , we label it **small**.
- 3.2 If the interval \mathbb{A}_i is *not* labeled as **unchecked**, we leave it intact, and exit.
- 3.3 Subdivide the parameter \mathbb{A}_i onto two equal parts; say $\mathbb{A}_{i,1}$ and $\mathbb{A}_{i,2}$. Both halves inherit the label of \mathbb{A}_i . For each of these parts, we perform the next steps.

- 3.4 Set $a = \text{mid}(\mathbb{A}_{i,j})$, and try to determine (non-rigorously) whether the map Q_a admits a stable orbit or not (of any period from the range $2, \dots, N$). If we are not able to find a good candidate for a stable orbit, we mark $\mathbb{A}_{i,j}$ as **unchecked**, and exit.
- 3.5 If we have a good candidate for stable orbit, we try to prove the existence of this orbit for the parameter domain $a + 10^{-17}[-1, 1]$. If this is not successful, we mark $\mathbb{A}_{i,j}$ as **unchecked** and exit.
- 3.6 Try to extend the existing stable orbit as much as possible to the left and to the right (this is what makes our partition non-uniform). Then insert to our partition the verified interval of stability, marked **verified**. If the verified domain of stability is not the entire interval $\mathbb{A}_{i,j}$, we also insert the remaining parts and mark them as **unchecked**.

Scanning for period doublings. In this step we traverse the current partition, and try to locate possible period doublings. For each candidate, we try to apply the method described in Section 3. If the method succeeds, we relabel the gap located between the two bounding stable windows as **periodDoubling**.

Collapsing data. In order to decrease the memory usage, we try to collapse windows which are connected, and on which we have the same verified period (it might happen that one window contains stability, the other period doubling).

5 Computational Results

In this final section, we present some quantitative results obtained from our computations.

In Table 1 we present information regarding the computed Lebesgue stability measure, the number of verified period doublings, and computational effort versus the subdivision level. From this table, it is apparent that proceeding with further subdivisions does not add much to the total stability measure, whereas the computational time increases significantly.

In order to obtain the stability measure reported in Theorem 1, we compute through 9 subdivision levels, with the restriction to the maximal period we are searching for as given in Table 1. We also compute through 18 subdivision levels with the restriction on the maximal period set to 33000, but with the older version of the C++ program, which did not contain the step of searching for superstable orbits. These latter computations took over one year of CPU time. We stress that this large computational effort is a consequence of us verifying the existence of orbits with relatively large periods (up to 33000). For such large periods, the corresponding stable windows do not contribute significantly to the total measure of the stability regions \mathcal{R} . Nevertheless, our aim is to maximize the lower bound of $|\mathcal{R}|$; not to be cost-effective. As a final step, we merge the data obtained from both computations. After merging the data, the number of verified period doublings numbered 95011.

| level | N | measure | wall time (h:m:s) | per. doublings |
|-------|------|------------------------|-------------------|----------------|
| 1 | 256 | 1.60620127942955014935 | 2 : 05 : 05 | 14 |
| 2 | 256 | 1.61118596303518551971 | 3 : 05 : 08 | 78 |
| 3 | 256 | 1.61287812977207803823 | 1 : 43 : 51 | 335 |
| 4 | 256 | 1.61349027421762439933 | 2 : 39 : 44 | 1381 |
| 5 | 256 | 1.61372268390076635341 | 5 : 18 : 22 | 4019 |
| 6 | 256 | 1.61381346643292467144 | 8 : 47 : 48 | 9075 |
| 7 | 512 | 1.61389940246044893686 | 67 : 26 : 04 | 20128 |
| 8 | 512 | 1.61391413966146151119 | 95 : 46 : 06 | 41692 |
| 9 | 1024 | 1.61393868758488911574 | 2 months | 89828 |

Table 1: Computational results in terms of the level of subdivision. Here, the reported wall time corresponds to the current subdivision level only, and is thus not the accumulated time. The listed values of the measure and period doublings, however, correspond to the accumulated amount from all previous levels.

In Table 2, we illustrate the fact that the parameter $a = 4$ is a (one-sided) Lebsgue density point of \mathcal{S} . As such, the relative measure of the regular parameters should tend to zero as the density point is approached.

| δ | $ \mathcal{R} \cap \mathbb{A}_\delta / \mathbb{A}_\delta $ | $-\log_{10}(\mathcal{R} \cap \mathbb{A}_\delta / \mathbb{A}_\delta)$ |
|-----------|--|--|
| 10^{-1} | 2.542×10^{-2} | 1.595 |
| 10^{-2} | 7.596×10^{-3} | 2.119 |
| 10^{-3} | 3.148×10^{-4} | 3.502 |
| 10^{-4} | 1.555×10^{-5} | 4.808 |
| 10^{-5} | 4.145×10^{-6} | 5.382 |
| 10^{-6} | 1.466×10^{-7} | 6.834 |

Table 2: The relative measure of the stable set, localised to increasingly small sets $\mathbb{A}_\delta = [4 - \delta, 4]$.

In Figure 2, we illustrate an interesting phenomenon; when we plot \log_2 of the period versus \log_{10} of the verified measure, all points appear to be confined within a wedge-shaped region. This was also observed in [ST91].

In Table 3 (see the Appendix) the verified lower bound for the total measure of stable windows with a given principal period is presented. Note that the measures do not sum to the total measure obtained in Theorem 1. This is because the sets on which the period doubling is verified is not taken into account in this table.

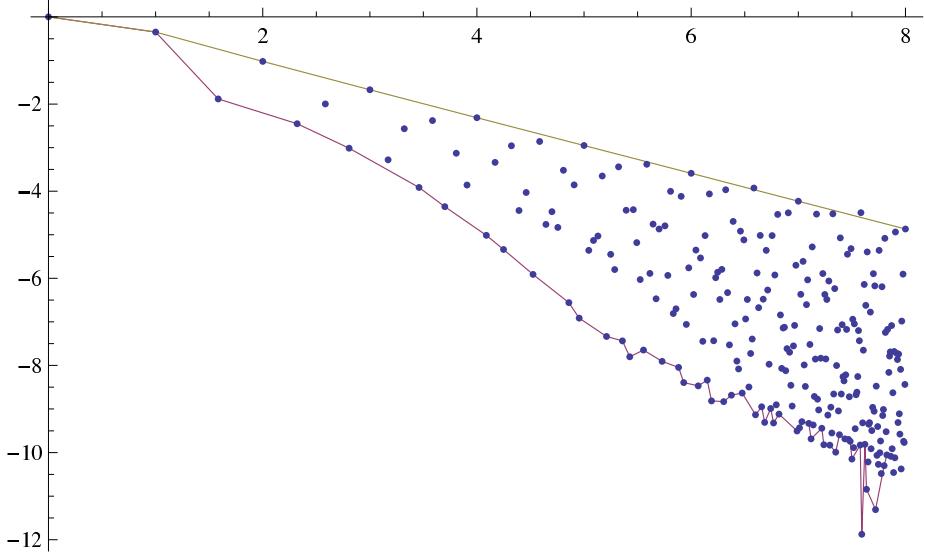


Figure 2: A plot of \log_2 of the period versus \log_{10} of the verified measure. Note how the prime periods form the lower line, whereas periods of the form 2^k form the upper line.

5.1 Implementation notes

The program realizing the computer assisted proof of Theorem 1 has been written by the authors, and the C++ source code is available to download at [W]. The program has been successfully compiled and run on a 32 CPU computer (8 2.2 GHz Athlon Quad Processors) under the Fedora 10 operating system. During all computations, we use `long double` precision. The code, however, is independent of the number type, and supports e.g. GMP formats too.

The output of the program contains information about the intervals on which we are able to verify stability or period doubling, together with rigorous enclosures for such orbits. The file with this data is about 61GB, and is available from the authors on request.

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Appendix

| p | N_w | verified measure | p | N_w | verified measure |
|-----|-------|----------------------------|-----|-------|----------------------------|
| 1 | 1 | 0.9999999999999999133 | 55 | 3834 | 1.16952087014289031475e-06 |
| 2 | 1 | 0.449489712730337562154 | 56 | 34696 | 9.88223384075245878805e-05 |
| 3 | 1 | 0.0130718827973174615657 | 57 | 7775 | 1.57651265319863273517e-07 |
| 4 | 2 | 0.0952673665554875199416 | 58 | 33002 | 2.04086492206802250227e-07 |
| 5 | 3 | 0.00352281749623573363014 | 59 | 2263 | 9.3960815970243332061e-09 |
| 6 | 5 | 0.0100535208500819814043 | 60 | 40112 | 7.60159858456679275035e-05 |
| 7 | 9 | 0.000970108705773774183598 | 61 | 1712 | 4.2499394036551313425e-09 |
| 8 | 16 | 0.0211991511740123133017 | 62 | 32056 | 9.15700806604358152896e-08 |
| 9 | 28 | 0.000524485461610248388312 | 63 | 8587 | 1.73677949005996735965e-06 |
| 10 | 51 | 0.00270572045435648776343 | 64 | 33904 | 0.000256549465339254555846 |
| 11 | 93 | 0.000121528614720657927514 | 65 | 1853 | 4.26198131763802154359e-07 |
| 12 | 170 | 0.00417709278913209851314 | 66 | 39564 | 4.45155419376936853371e-06 |
| 13 | 314 | 4.41799281499500023224e-05 | 67 | 980 | 3.5057975281485576069e-09 |
| 14 | 583 | 0.000745338242653109531513 | 68 | 34003 | 2.93812095214789244235e-06 |
| 15 | 1081 | 0.00013866411367281154636 | 69 | 9099 | 3.72479415880911518544e-08 |
| 16 | 2001 | 0.000484464029931238248858 | 70 | 30358 | 9.57473156841894858238e-06 |
| 17 | 3674 | 9.73054144422376941781e-06 | 71 | 599 | 4.69818209791923735441e-09 |
| 18 | 6571 | 0.000459303691807767637545 | 72 | 42865 | 8.63683164619860350292e-05 |
| 19 | 11206 | 4.62585472593029546629e-06 | 73 | 481 | 2.02193056329964815365e-09 |
| 20 | 17602 | 0.00110323675556129436291 | 74 | 25233 | 3.78680588667985179585e-08 |
| 21 | 26270 | 3.58681690089041917135e-05 | 75 | 10964 | 1.03411117788700969433e-06 |
| 22 | 35999 | 9.30300639218476551479e-05 | 76 | 31668 | 1.38456132692103307813e-06 |
| 23 | 37228 | 1.25536973051955727532e-06 | 77 | 1242 | 3.26382623013713596416e-07 |
| 24 | 54621 | 0.00138359311074481676485 | 78 | 30007 | 1.60349387493246425818e-06 |
| 25 | 53658 | 1.72318055346306828191e-05 | 79 | 331 | 1.8987512540990375536e-09 |
| 26 | 71167 | 3.38041935882169800737e-05 | 80 | 33257 | 0.000107430044875180116457 |
| 27 | 85069 | 1.4731351237678731031e-05 | 81 | 9330 | 4.7157074870756224283e-07 |
| 28 | 90545 | 0.000302802777599259741181 | 82 | 15542 | 3.05558143936807830032e-08 |
| 29 | 70699 | 2.92616749706254425378e-07 | 83 | 193 | 2.75592126463414244242e-09 |
| 30 | 72811 | 0.000139073782564788119009 | 84 | 38462 | 2.01670921383297063745e-05 |
| 31 | 49998 | 3.12487884997936622433e-07 | 85 | 3884 | 9.05240564882080211984e-08 |
| 32 | 51460 | 0.00111489583255148854909 | 86 | 10550 | 1.35961065155908861213e-08 |
| 33 | 51338 | 4.37407428109876442179e-06 | 87 | 8993 | 8.67064942349123068954e-09 |
| 34 | 52969 | 7.41426465505293924574e-06 | 88 | 26053 | 1.2129835051315034089e-05 |
| 35 | 51517 | 9.33206508702726436622e-06 | 89 | 98 | 2.39681285821129186342e-09 |
| 36 | 54577 | 0.000222757503877830161793 | 90 | 24006 | 7.60450007215125386995e-06 |
| 37 | 48407 | 4.88544719043620262466e-08 | 91 | 1998 | 1.16842960114346347544e-07 |
| 38 | 53694 | 3.54432509872947693053e-06 | 92 | 22564 | 3.2889032366045962974e-07 |
| 39 | 42923 | 1.58656653860079002727e-06 | 93 | 8526 | 3.3245223369321807741e-09 |
| 40 | 52635 | 0.000360875968039200316698 | 94 | 5041 | 1.91490069276472468784e-08 |
| 41 | 36336 | 3.77527918547174851094e-08 | 95 | 5369 | 4.09062863484643129963e-08 |
| 42 | 50684 | 3.65605909414580283051e-05 | 96 | 34853 | 0.000117737286417092437002 |
| 43 | 28864 | 1.69450330377539370996e-08 | 97 | 44 | 9.6037879840533968423e-10 |
| 44 | 47615 | 3.75116589486691222322e-05 | 98 | 6033 | 1.32695184839161720025e-06 |
| 45 | 21957 | 6.61146604233418117014e-06 | 99 | 9140 | 2.12315322532059466698e-07 |
| 46 | 43808 | 9.44120952634311394469e-07 | 100 | 26510 | 9.65785966405342290175e-06 |
| 47 | 14255 | 2.30083172458005191796e-08 | 101 | 33 | 1.48979659533345076827e-09 |
| 48 | 42503 | 0.000415087370009211385768 | 102 | 14987 | 3.32312031203416125003e-07 |
| 49 | 9915 | 1.29714218588755994532e-06 | 103 | 35 | 6.26427760141642919756e-10 |
| 50 | 38085 | 1.75737844581981637188e-05 | 104 | 21894 | 4.37396446778320555082e-06 |
| 51 | 9566 | 3.41429440874627468383e-07 | 105 | 15452 | 5.39741123959215987616e-07 |
| 52 | 36585 | 1.35894747589091011847e-05 | 106 | 1846 | 1.081138791252794773e-08 |
| 53 | 5303 | 1.26399147778229886674e-08 | 107 | 27 | 1.3589323455831132759e-09 |
| 54 | 38727 | 1.59944966324214628284e-05 | 108 | 33467 | 9.58279471456168624455e-06 |
| | | | 109 | 19 | 5.89864870923634265765e-10 |

| p | N_w | verified measure | p | N_w | verified measure |
|-----|-------|----------------------------|-----|-------|----------------------------|
| 110 | 10150 | 1.19038627957698990578e-06 | 169 | 2552 | 2.23272062990775843616e-09 |
| 111 | 4657 | 1.33885744092905600855e-09 | 170 | 11995 | 8.61908283987088824629e-08 |
| 112 | 25245 | 2.93651594566893357069e-05 | 171 | 5301 | 5.61112843623819135264e-09 |
| 113 | 22 | 7.62790269967159040299e-10 | 172 | 3013 | 4.68261720869798947486e-09 |
| 114 | 14037 | 1.44886106519638915846e-07 | 173 | 4 | 2.05689922993385065908e-10 |
| 115 | 6379 | 8.9113670026074592867e-09 | 174 | 9899 | 6.12742601146035181792e-09 |
| 116 | 17449 | 7.36887705993227726253e-08 | 175 | 7178 | 6.69645084715262545183e-08 |
| 117 | 6022 | 7.55974681727975689194e-08 | 176 | 21688 | 3.57028187807518354591e-06 |
| 118 | 855 | 7.6775308235476485974e-09 | 177 | 111 | 2.09676764449315267136e-10 |
| 119 | 4457 | 2.4378422289758963637e-08 | 178 | 28 | 1.91676241458743623625e-09 |
| 120 | 43913 | 3.1888155035223562284e-05 | 179 | 1 | 1.81419202577304261581e-10 |
| 121 | 1712 | 2.01468847724553534739e-08 | 180 | 37873 | 4.79193552861841530477e-06 |
| 122 | 684 | 3.88504109156799504188e-09 | 181 | 2 | 7.09528416922844407111e-11 |
| 123 | 1979 | 1.17893921296359505124e-09 | 182 | 11798 | 1.1485544300165149989e-07 |
| 124 | 16585 | 2.86872655920998587131e-08 | 183 | 90 | 1.31884991859745892562e-10 |
| 125 | 6388 | 8.27675618213837699377e-08 | 184 | 14009 | 9.11574432392418809723e-08 |
| 126 | 21280 | 1.99476268637191131439e-06 | 185 | 1472 | 3.6963785938343152182e-10 |
| 127 | 10 | 3.11803653426159788076e-10 | 186 | 8445 | 2.14654189540329498609e-09 |
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| 594 | 3767 | 6.9994637444999868725e-09 | 700 | 3679 | 5.10405214651336869291e-08 |
| 595 | 606 | 1.03685408566270287345e-10 | 702 | 2041 | 1.27188469868991238521e-09 |
| 596 | 1 | 1.61110708107869982086e-13 | 704 | 6733 | 2.39798847709304929765e-07 |
| 598 | 361 | 1.05182440448409186828e-11 | 705 | 6 | 2.92462516877922684699e-12 |
| 600 | 15095 | 4.18218123712310943518e-07 | 708 | 4 | 2.14708199136603994361e-12 |
| 602 | 19 | 2.9942602217145334028e-12 | 710 | 2 | 2.78729817004830238147e-12 |
| 604 | 1 | 1.13650885577576410412e-12 | 712 | 2 | 3.44888679247590257404e-11 |
| 605 | 480 | 1.32555783190213549716e-10 | 714 | 1431 | 3.61813527922916211566e-10 |
| 608 | 4374 | 2.04285658239860418162e-08 | 715 | 457 | 3.62098382961778542111e-11 |
| 609 | 76 | 4.23626910460439543016e-12 | 716 | 1 | 1.8762536663219364641e-11 |
| 610 | 1 | 1.72474881598994045362e-14 | 718 | 1 | 1.15963705651922488471e-11 |
| 611 | 1 | 2.46354586036501288504e-14 | 720 | 19213 | 8.6429333542251823852e-07 |
| 612 | 5061 | 4.13196899915965754069e-09 | 722 | 59 | 3.1730347516134571606e-13 |
| 615 | 10 | 2.2658177417644864704e-13 | 725 | 19 | 6.12616294498602442786e-13 |
| 616 | 8532 | 5.80411969985494130553e-08 | 726 | 924 | 3.34178100989956927691e-10 |
| 618 | 2 | 2.97640406245192057355e-12 | 728 | 4729 | 1.26551819540181298418e-08 |
| 620 | 434 | 1.16514998387343138297e-10 | 729 | 138 | 1.95599015716946267318e-10 |
| 621 | 195 | 7.49198880017898360961e-12 | 730 | 2 | 4.18040168453925886638e-14 |
| 624 | 9613 | 1.11065251645137488823e-07 | 732 | 2 | 2.14005679496920286908e-13 |
| 625 | 136 | 3.33101014436329445623e-10 | 735 | 518 | 9.76086386847083153917e-10 |
| 627 | 278 | 4.88968761314101385551e-12 | 736 | 1434 | 3.44510321767695082418e-09 |
| 628 | 1 | 1.09057467917450523487e-12 | 738 | 14 | 5.30566693010547929532e-12 |
| 629 | 1 | 1.62456853525227984392e-15 | 740 | 57 | 2.81590068103299007163e-11 |
| 630 | 7956 | 3.56993611597047205697e-08 | 741 | 89 | 5.72940566517798899326e-13 |
| 632 | 4 | 2.85736783626339141406e-11 | 742 | 3 | 4.77231904168207154981e-12 |
| 636 | 18 | 5.01058127280740173148e-11 | 744 | 251 | 1.25631554421731794768e-10 |

| p | N_w | verified measure | p | N_w | verified measure |
|-----|-------|-----------------------------|------|-------|----------------------------|
| 748 | 1408 | 1.50992142617170643781e-10 | 884 | 409 | 1.19631114910145885943e-11 |
| 750 | 1344 | 7.56329652943157904055e-09 | 888 | 31 | 5.75977980588060489708e-12 |
| 752 | 27 | 2.86284443417120226805e-10 | 891 | 205 | 4.88868116994833901146e-11 |
| 754 | 20 | 1.62976403206283038116e-13 | 896 | 5012 | 5.48941543476602969442e-07 |
| 756 | 6432 | 4.79394160867851332197e-08 | 897 | 8 | 3.74479093567803289488e-14 |
| 759 | 31 | 3.95866282462686847055e-13 | 900 | 4438 | 4.07473651951005544358e-08 |
| 760 | 1902 | 1.89107960367473904029e-09 | 902 | 3 | 2.52011952972530650641e-14 |
| 765 | 343 | 3.31896912297152679727e-11 | 903 | 1 | 2.80981835021343329117e-15 |
| 768 | 8604 | 2.18189426485549710366e-06 | 904 | 2 | 1.64998425079138089089e-11 |
| 770 | 2004 | 2.7520980945501108744e-09 | 906 | 1 | 1.52516888007880879741e-14 |
| 774 | 8 | 1.16522633555882215717e-12 | 910 | 776 | 3.02234676305065952384e-10 |
| 775 | 6 | 9.12551284537599372015e-15 | 912 | 1428 | 2.64289139141268836219e-09 |
| 777 | 5 | 2.59859408296980731734e-13 | 913 | 1 | 6.46264725762124569997e-14 |
| 780 | 4462 | 7.28152923026859077993e-09 | 915 | 1 | 1.58987406573274370203e-15 |
| 782 | 31 | 2.15576688444851782833e-13 | 918 | 531 | 5.47849354857327108803e-11 |
| 783 | 13 | 4.58466381178523896267e-13 | 920 | 481 | 2.5668242162844856491e-10 |
| 784 | 3628 | 9.21655887939094170536e-08 | 924 | 2656 | 4.36216550706546024596e-09 |
| 792 | 6934 | 3.99928623729013665855e-08 | 925 | 1 | 2.85192876259277028339e-14 |
| 793 | 1 | 2.05955044685346422284e-15 | 928 | 222 | 5.91796759383603210303e-10 |
| 798 | 759 | 8.80575736026539823698e-11 | 930 | 19 | 9.11678068107879546744e-13 |
| 800 | 5548 | 4.57099504875841528007e-07 | 931 | 25 | 4.63697873501200952262e-13 |
| 804 | 4 | 7.40543694074946579065e-12 | 935 | 74 | 1.1840131739632164809e-12 |
| 805 | 65 | 1.54558592486975232561e-12 | 936 | 3392 | 7.54518250200945927997e-09 |
| 806 | 4 | 1.93443351614863701116e-15 | 938 | 1 | 2.00197931149448393739e-14 |
| 808 | 1 | 2.31145202804483584913e-11 | 940 | 5 | 2.36675132617159000858e-12 |
| 810 | 2531 | 7.82668530636618231533e-09 | 944 | 3 | 3.19315060504088421567e-12 |
| 812 | 114 | 3.9553866909222690218e-11 | 945 | 461 | 5.23403440163758282289e-10 |
| 814 | 3 | 1.46636825945622994993e-13 | 950 | 201 | 2.38799997571287336839e-11 |
| 816 | 2701 | 8.72972972642410693922e-09 | 952 | 1116 | 6.44693606876092784042e-10 |
| 819 | 373 | 6.59180286310262486538e-11 | 957 | 3 | 5.35474442564520813903e-14 |
| 820 | 15 | 1.82129912280198924535e-11 | 960 | 10269 | 1.09647653844121249767e-06 |
| 824 | 1 | 2.50777480378938655292e-13 | 962 | 3 | 2.20977749987305571722e-14 |
| 825 | 404 | 2.8227400299986327159e-10 | 966 | 164 | 6.19565076326322738964e-12 |
| 826 | 1 | 8.99280649946376797743e-15 | 968 | 975 | 8.25539695848212518037e-10 |
| 828 | 670 | 1.22388641322218605367e-10 | 969 | 3 | 1.10918219053957045617e-14 |
| 830 | 1 | 6.370555125090326955334e-15 | 972 | 1315 | 6.16193178188013945817e-09 |
| 832 | 3600 | 6.89918706682675353381e-08 | 975 | 158 | 2.37665922098867499201e-11 |
| 833 | 58 | 3.21869354086290471173e-12 | 976 | 2 | 6.35772901338982343589e-13 |
| 836 | 635 | 3.62297210461381968827e-11 | 980 | 1249 | 8.92045035776924122306e-09 |
| 837 | 1 | 1.38387565296049785957e-15 | 984 | 6 | 1.45336735268147831945e-11 |
| 840 | 9844 | 1.81910378552196938529e-07 | 986 | 4 | 2.06468956515104551386e-14 |
| 845 | 65 | 1.0787484187174678496e-12 | 987 | 1 | 3.02997644335833982154e-14 |
| 846 | 4 | 5.86597177082426313177e-13 | 988 | 187 | 2.42684951995419950777e-12 |
| 847 | 95 | 7.2785443037265418198e-12 | 990 | 1631 | 1.02758240783616672243e-09 |
| 848 | 9 | 2.38588763112543289502e-10 | 992 | 109 | 1.71481747421667329867e-10 |
| 850 | 409 | 1.03452779762897018045e-10 | 996 | 2 | 3.109483807592350324e-12 |
| 854 | 2 | 3.50107963453805126619e-13 | 999 | 2 | 2.92064549628490155442e-14 |
| 855 | 184 | 6.33060032347032564104e-12 | 1000 | 1111 | 2.92516899702121441207e-08 |
| 858 | 918 | 9.70563900516002719954e-11 | 1001 | 63 | 1.10894344922118914809e-12 |
| 860 | 7 | 3.59931008608871394472e-12 | 1008 | 7140 | 1.75993060460731196026e-07 |
| 861 | 1 | 4.73371342124551119923e-14 | 1012 | 96 | 4.88267998081937104615e-12 |
| 864 | 9039 | 5.56894825449062019773e-07 | 1014 | 200 | 4.8241792505177016892e-12 |
| 867 | 10 | 7.55010203662420664728e-14 | 1015 | 6 | 2.20514578819219764227e-13 |
| 868 | 49 | 3.4550149199952251422e-12 | 1020 | 1025 | 3.52777066239817749249e-10 |
| 870 | 101 | 1.30182648515331234051e-11 | 1024 | 2052 | 6.91056137385685081975e-07 |
| 874 | 8 | 6.76357841261632231067e-14 | 1040 | 16 | 7.44776625354742760621e-11 |
| 875 | 90 | 2.9289056141350300333e-10 | 1050 | 7 | 6.47966142547362622395e-11 |
| 880 | 4583 | 5.88084942915265834751e-08 | 1056 | 76 | 7.7612096313541684145e-09 |
| 882 | 1350 | 3.01455380601577116462e-09 | 1072 | 1 | 7.05499872931392157938e-12 |

| p | N_w | verified measure | p | N_w | verified measure |
|------|-------|----------------------------|------|-------|----------------------------|
| 1080 | 138 | 1.26050035227295853524e-08 | 1824 | 4 | 8.06646416329215298902e-17 |
| 1088 | 5 | 4.27856838283377505228e-10 | 1848 | 4 | 8.06646416329215298902e-17 |
| 1092 | 1 | 2.01661604082303824725e-17 | 1872 | 6 | 1.20996962449382294835e-16 |
| 1100 | 5 | 4.45526298145648702587e-12 | 1904 | 1 | 2.01661604082303824725e-17 |
| 1104 | 1 | 2.01661604082303824725e-17 | 1920 | 262 | 2.163420860449693367e-07 |
| 1120 | 156 | 1.26051267759818078074e-07 | 1944 | 9 | 1.81495443674073442253e-16 |
| 1125 | 1 | 2.01661604082303824725e-17 | 1960 | 4 | 1.40516183758099266754e-11 |
| 1134 | 1 | 5.26686875536308551915e-12 | 1980 | 1 | 2.01661604082303824725e-17 |
| 1140 | 1 | 2.01661604082303824725e-17 | 2000 | 15 | 1.29177164234425823075e-09 |
| 1144 | 1 | 2.01661604082303824725e-17 | 2016 | 125 | 4.52573798142424932323e-09 |
| 1152 | 255 | 6.10567644449304045007e-07 | 2040 | 3 | 6.04984812246911474176e-17 |
| 1170 | 1 | 2.01661604082303824725e-17 | 2048 | 43 | 1.35853521534765042666e-07 |
| 1176 | 24 | 5.56366844088607148677e-10 | 2080 | 5 | 1.00830802041151912363e-16 |
| 1184 | 1 | 2.01661604082303824725e-17 | 2100 | 8 | 1.6132928326584305978e-16 |
| 1188 | 2 | 4.03323208164607649451e-17 | 2112 | 22 | 2.01244349526744081835e-10 |
| 1200 | 157 | 5.58073092254366548426e-08 | 2156 | 1 | 2.01661604082303824725e-17 |
| 1215 | 1 | 2.01661604082303824725e-17 | 2160 | 92 | 1.56601677936060723617e-09 |
| 1216 | 3 | 1.59302432356511758371e-12 | 2176 | 1 | 2.01661604082303824725e-17 |
| 1224 | 4 | 8.06646416329215298902e-17 | 2184 | 1 | 2.01661604082303824725e-17 |
| 1232 | 24 | 4.69212817471448273565e-11 | 2200 | 4 | 8.06646416329215298902e-17 |
| 1248 | 25 | 2.34445507712316425497e-10 | 2240 | 89 | 1.89759388814249307931e-08 |
| 1260 | 22 | 5.99486903261198245119e-11 | 2268 | 2 | 4.03323208164607649451e-17 |
| 1280 | 153 | 4.29530000367519398941e-07 | 2304 | 187 | 1.46981382817372441263e-07 |
| 1296 | 88 | 9.42396631803225914847e-09 | 2340 | 1 | 2.01661604082303824725e-17 |
| 1300 | 1 | 2.01661604082303824725e-17 | 2352 | 12 | 2.62160085306994972143e-16 |
| 1320 | 18 | 2.09381784913725832453e-11 | 2376 | 2 | 4.03323208164607649451e-17 |
| 1344 | 181 | 1.70660756297841623153e-07 | 2400 | 121 | 7.68120562294472090057e-09 |
| 1350 | 1 | 1.64668621620289723495e-11 | 2464 | 2 | 4.03323208164607649451e-17 |
| 1352 | 1 | 2.01661604082303824725e-17 | 2496 | 5 | 1.00830802041151912363e-16 |
| 1360 | 2 | 4.03323208164607649451e-17 | 2520 | 19 | 3.83157047756377266978e-16 |
| 1368 | 2 | 4.03323208164607649451e-17 | 2560 | 99 | 9.52879874516806418816e-08 |
| 1372 | 2 | 4.03323208164607649451e-17 | 2592 | 56 | 4.48746794497884016195e-10 |
| 1386 | 1 | 2.01661604082303824725e-17 | 2640 | 5 | 1.00830802041151912363e-16 |
| 1392 | 1 | 3.93118697317174081718e-14 | 2688 | 119 | 2.46360268030005463702e-08 |
| 1400 | 25 | 1.32888534074351860603e-09 | 2700 | 6 | 1.20996962449382294835e-16 |
| 1408 | 41 | 1.35467981270554621576e-08 | 2720 | 1 | 2.01661604082303824725e-17 |
| 1428 | 1 | 2.01661604082303824725e-17 | 2800 | 18 | 9.85830763810396915048e-11 |
| 1440 | 292 | 1.19849110882547932322e-07 | 2816 | 14 | 3.9972266664169142647e-10 |
| 1456 | 3 | 6.04984812246911474176e-17 | 2880 | 224 | 1.57514175023500124784e-08 |
| 1458 | 2 | 4.03323208164607649451e-17 | 2912 | 2 | 4.03323208164607649451e-17 |
| 1500 | 11 | 7.61010807322215487858e-11 | 2940 | 1 | 2.01661604082303824725e-17 |
| 1512 | 19 | 1.0492414099019797824e-10 | 3000 | 7 | 1.41163122857612677308e-16 |
| 1520 | 2 | 4.03323208164607649451e-17 | 3024 | 18 | 3.62990887348146884506e-16 |
| 1536 | 170 | 4.36508358502354920638e-07 | 3040 | 1 | 2.01661604082303824725e-17 |
| 1540 | 4 | 8.06646416329215298902e-17 | 3072 | 103 | 9.33353577474860945928e-08 |
| 1560 | 4 | 8.06646416329215298902e-17 | 3120 | 1 | 2.01661604082303824725e-17 |
| 1568 | 29 | 4.11252392557015511443e-09 | 3136 | 13 | 9.7852865133668531783e-11 |
| 1584 | 13 | 7.48487556656574071212e-12 | 3168 | 10 | 2.01661604082303824725e-16 |
| 1600 | 93 | 8.37857453239547467216e-08 | 3200 | 67 | 1.13766802092244573297e-08 |
| 1620 | 12 | 2.4729293985509283114e-11 | 3240 | 6 | 1.20996962449382294835e-16 |
| 1632 | 4 | 1.75302552422179624969e-11 | 3328 | 5 | 1.00830802041151912363e-16 |
| 1664 | 10 | 3.41086777528795681569e-10 | 3360 | 61 | 8.18627051996784205201e-11 |
| 1680 | 121 | 5.40150254342217084336e-09 | 3456 | 133 | 1.13324545385727615265e-08 |
| 1728 | 208 | 9.33806746942957704993e-08 | 3520 | 8 | 1.6132928326584305978e-16 |
| 1744 | 1 | 2.350438047355386999e-12 | 3528 | 1 | 2.01661604082303824725e-17 |
| 1760 | 21 | 7.20544088804453419783e-11 | 3584 | 41 | 1.46504951935213373337e-08 |
| 1764 | 1 | 2.01661604082303824725e-17 | 3600 | 24 | 2.22905021263902769491e-11 |
| 1792 | 65 | 9.26499040202876517069e-08 | 3640 | 1 | 2.01661604082303824725e-17 |
| 1800 | 50 | 7.92415121584136294963e-10 | 3696 | 1 | 2.01661604082303824725e-17 |

| p | N_w | verified measure | p | N_w | verified measure |
|-------|-------|-----------------------------|-------|-------|----------------------------|
| 3780 | 2 | 4.03323208164607649451e-17 | 10368 | 5 | 1.00830802041151912363e-16 |
| 3840 | 165 | 3.35846411221672053182e-08 | 10752 | 25 | 5.8277964702299622779e-11 |
| 3888 | 5 | 1.00830802041151912363e-16 | 11200 | 1 | 2.01661604082303824725e-17 |
| 3920 | 2 | 4.03323208164607649451e-17 | 11264 | 1 | 2.01661604082303824725e-17 |
| 3960 | 1 | 2.01661604082303824725e-17 | 11520 | 50 | 3.45301736422859439912e-11 |
| 4000 | 13 | 1.18540902788177859861e-10 | 12288 | 25 | 2.52287638046258533286e-09 |
| 4032 | 60 | 1.91539026826725855557e-10 | 12544 | 1 | 2.01661604082303824725e-17 |
| 4096 | 27 | 2.24732561321123319731e-08 | 12800 | 7 | 1.6132928326584305978e-16 |
| 4160 | 1 | 2.01661604082303824725e-17 | 13440 | 5 | 1.00830802041151912363e-16 |
| 4200 | 4 | 8.06646416329215298902e-17 | 13824 | 30 | 3.00239722406808740018e-11 |
| 4224 | 15 | 4.4083660332606102867e-16 | 14336 | 7 | 3.0324076799939647664e-11 |
| 4320 | 41 | 6.33671505025079628837e-11 | 15360 | 30 | 1.3809309164919403301e-10 |
| 4416 | 1 | 2.01661604082303824725e-17 | 16000 | 1 | 2.01661604082303824725e-17 |
| 4480 | 47 | 4.44286632657331370666e-10 | 16128 | 2 | 4.03323208164607649451e-17 |
| 4500 | 1 | 2.01661604082303824725e-17 | 16384 | 2 | 4.58952424241959588969e-10 |
| 4608 | 109 | 2.75429096201380840814e-08 | 17280 | 1 | 2.01661604082303824725e-17 |
| 4704 | 4 | 8.06646416329215298902e-17 | 17920 | 7 | 1.41163122857612677308e-16 |
| 4752 | 1 | 2.01661604082303824725e-17 | 18432 | 19 | 7.0838524282579307112e-11 |
| 4800 | 59 | 4.650150830804583357934e-10 | 19200 | 1 | 2.01661604082303824725e-17 |
| 4928 | 2 | 4.03323208164607649451e-17 | 20480 | 6 | 1.48670596666899967886e-10 |
| 4992 | 4 | 8.06646416329215298902e-17 | 21504 | 4 | 8.06646416329215298902e-17 |
| 5000 | 1 | 2.01661604082303824725e-17 | 23040 | 1 | 2.01661604082303824725e-17 |
| 5040 | 8 | 1.6132928326584305978e-16 | 24576 | 7 | 1.96098825112206442967e-10 |
| 5120 | 46 | 1.69437647755659587245e-08 | 25600 | 1 | 2.01661604082303824725e-17 |
| 5184 | 27 | 3.28448097712541464688e-12 | 27648 | 3 | 6.04984812246911474176e-17 |
| 5280 | 2 | 4.03323208164607649451e-17 | 28672 | 2 | 4.03323208164607649451e-17 |
| 5376 | 71 | 1.5143025967285917594e-09 | | | |
| 5400 | 2 | 4.03323208164607649451e-17 | | | |
| 5600 | 6 | 1.20996962449382294835e-16 | | | |
| 5632 | 2 | 4.03323208164607649451e-17 | | | |
| 5760 | 111 | 1.09496048512902621752e-09 | | | |
| 6000 | 5 | 1.00830802041151912363e-16 | | | |
| 6048 | 4 | 8.06646416329215298902e-17 | | | |
| 6144 | 58 | 1.70946220685863625732e-08 | | | |
| 6272 | 3 | 6.04984812246911474176e-17 | | | |
| 6300 | 1 | 2.01661604082303824725e-17 | | | |
| 6336 | 2 | 4.03323208164607649451e-17 | | | |
| 6400 | 38 | 6.63067415210272237402e-10 | | | |
| 6480 | 4 | 8.06646416329215298902e-17 | | | |
| 6720 | 17 | 3.42824726939916502033e-16 | | | |
| 6912 | 80 | 8.68082543131407091686e-10 | | | |
| 7040 | 1 | 2.01661604082303824725e-17 | | | |
| 7168 | 23 | 9.41381698288390467155e-10 | | | |
| 7200 | 12 | 2.62160085306994972143e-16 | | | |
| 7680 | 78 | 3.80943674846943858281e-09 | | | |
| 7776 | 1 | 2.01661604082303824725e-17 | | | |
| 7840 | 2 | 4.03323208164607649451e-17 | | | |
| 8000 | 7 | 1.41163122857612677308e-16 | | | |
| 8064 | 28 | 4.11358252148941172521e-12 | | | |
| 8192 | 8 | 4.29929311379292911077e-09 | | | |
| 8400 | 2 | 4.03323208164607649451e-17 | | | |
| 8448 | 5 | 1.00830802041151912363e-16 | | | |
| 8640 | 8 | 1.6132928326584305978e-16 | | | |
| 8960 | 14 | 2.82326245715225354616e-16 | | | |
| 9216 | 63 | 2.5629170070928797287e-09 | | | |
| 9408 | 2 | 4.03323208164607649451e-17 | | | |
| 9600 | 23 | 4.30581091614978817006e-12 | | | |
| 10080 | 1 | 2.01661604082303824725e-17 | | | |
| 10240 | 30 | 2.16034582193810886785e-09 | | | |

Table 3: The lower bound of the total stability measure of windows with respect to the principal period p . Also the number of detected windows N_w is given. This means that we found N_w distinct orbits of principal period p . The total number of verified sinks is 4970355.